

Groupe de travail Dyliss

**Analysis of Biological Networks:
A Summary of my Works**

Analyse des réseaux biologiques: un résumé de mes travaux

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Overview of This Presentation

Frameworks: modeling biological processes

- **Thomas modeling** (historically widespread)
- **Asynchronous Automata Networks** (generalization)
- **Hybrid Thomas modeling** (generalization)

Model completion: inferring missing information on the model

- **Hybrid Hoare logic** (parameters/logical gates on Hybrid Thomas modeling)
- **Continuous transitions** (logical thresholds from expression profiles)

Dynamic analyses: explore the dynamics of a model

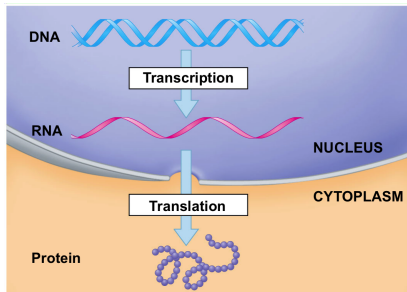
- **μ -calculus & Answer Set Programming** (exhaustive)
- **Abstract interpretation** (approximations)

TGF- β pathways project: my work here as a postdoc

- Extract and build a big graph from databases
- Search for inconsistencies in cancerous types

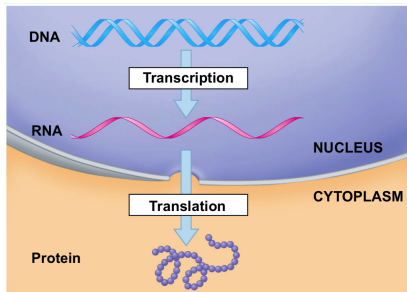
Frameworks

Abstractions of the Representation

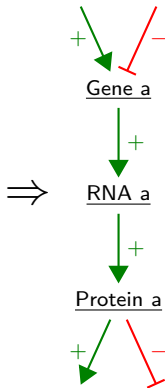


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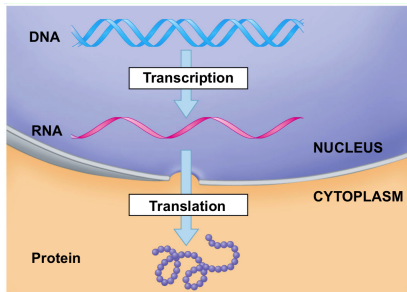
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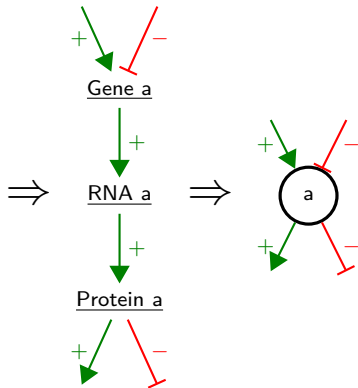
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Abstractions of the Representation



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Discrete Networks / Thomas Modeling

[Kauffman, *Journal of Theoretical Biology*, 1969]

[Thomas, *Journal of Theoretical Biology*, 1973]

- A set of components $N = \{a, b, z\}$



Discrete Networks / Thomas Modeling

[Kauffman, *Journal of Theoretical Biology*, 1969][Thomas, *Journal of Theoretical Biology*, 1973]

- A set of components $N = \{a, b, z\}$
- A set of discrete expression levels for each component $a \in \mathbb{F}^a = \llbracket 0; 2 \rrbracket$
- The set of global states $\mathbb{F} = \mathbb{F}^a \times \mathbb{F}^b \times \mathbb{F}^z$

 $\llbracket 0; 2 \rrbracket$  $\llbracket 0; 1 \rrbracket$  $\llbracket 0; 1 \rrbracket$

Discrete Networks / Thomas Modeling

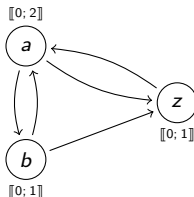
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- The set of global states $\mathbb{F} = \mathbb{F}^a \times \mathbb{F}^b \times \mathbb{F}^z$
- An evolution function for each component $f^z : \mathbb{F} \rightarrow \mathbb{F}^z$

a	$f^b(a)$
0	0
1	1
2	1

z	b	$f^a(z, b)$
0	0	1
0	1	0
1	0	1
1	1	2

a	b	$f^z(a, b)$
0	0	0
0	1	0
1	0	0
1	1	0
2	0	0
2	1	1



Discrete Networks / Thomas Modeling

[Kauffman, *Journal of Theoretical Biology*, 1969][Thomas, *Journal of Theoretical Biology*, 1973]

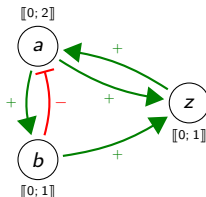
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 $\llbracket 0; 2 \rrbracket$  $\llbracket 0; 1 \rrbracket$  $\llbracket 0; 1 \rrbracket$

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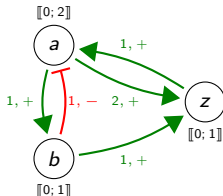
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- Signs on the edges $a \xrightarrow{+} z$



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- Signs on the edges $a \xrightarrow{+} z$ or signs & thresholds $a \xrightarrow{2,+} z$

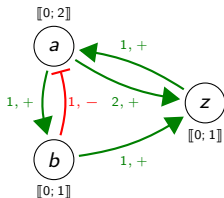


Discrete Networks / Thomas Modeling

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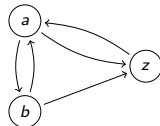
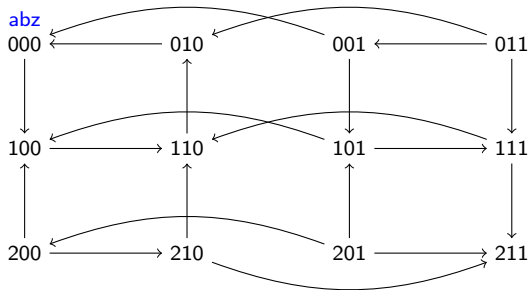
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- Signs on the edges $a \xrightarrow{+} z$ or signs & thresholds $a \xrightarrow{2,+} z$
- Discrete parameters / evolution functions $f^a : \mathbb{F} \rightarrow \mathbb{F}^a$

a	$f^b(a)$	z	b	$f^a(z, b)$	a	b	$f^z(a, b)$
0	0	0	0	1	0	0	0
1	1	0	1	0	0	1	0
2	1	1	0	1	1	0	0
		1	1	2	1	1	0
					2	0	0
					2	1	1



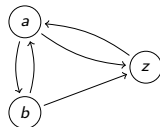
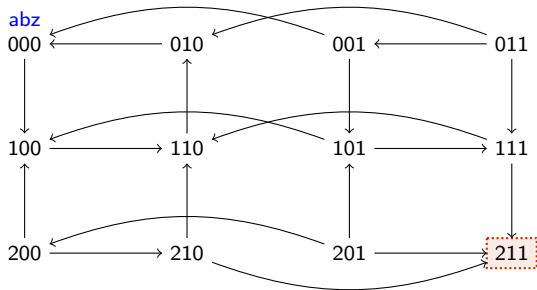
State-graph

The state-graph depicts the whole dynamics
 Computation: **exponential** in the size of the model



State-graph

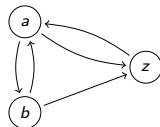
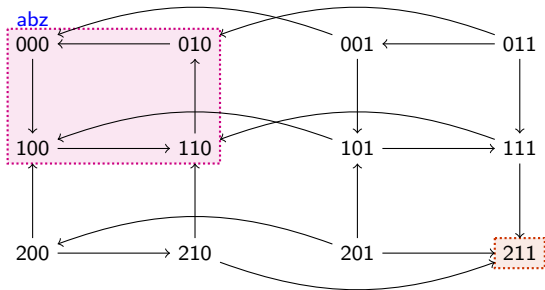
The state-graph depicts the whole dynamics
 Computation: **exponential** in the size of the model



- **Stable state** = state with no successors

State-graph

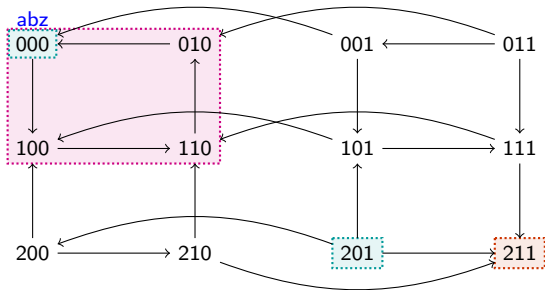
The state-graph depicts the whole dynamics
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- **Stable state** = state with no successors
- **Complex attractor** = minimal loop or composition of loops from which the dynamics cannot escape

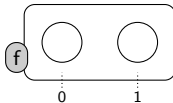
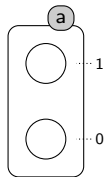
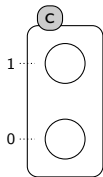
State-graph

The state-graph depicts the whole dynamics
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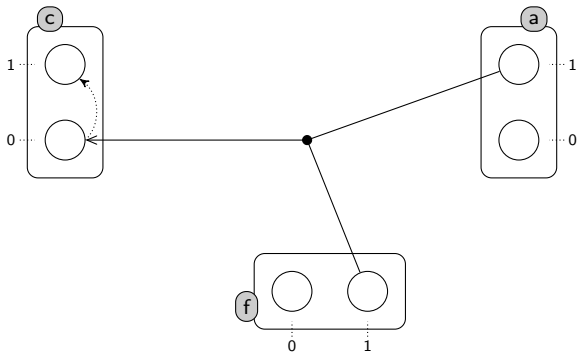


- **Stable state** = state with no successors
- **Complex attractor** = minimal loop or composition of loops from which the dynamics cannot escape
- **Reachability** = from **000**, can I reach **201**?

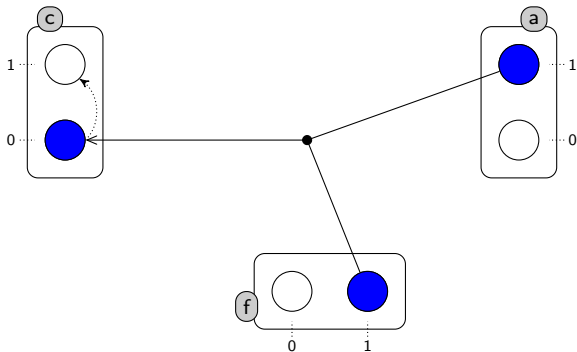
Asynchronous Automata Networks (AAN) Enriched Process Hitting (PH)



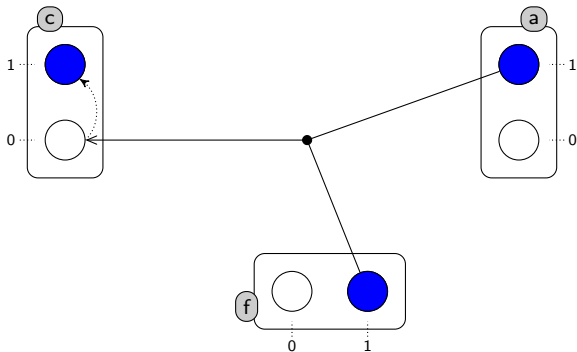
Asynchronous Automata Networks (AAN) Enriched Process Hitting (PH)



Asynchronous Automata Networks (AAN) Enriched Process Hitting (PH)

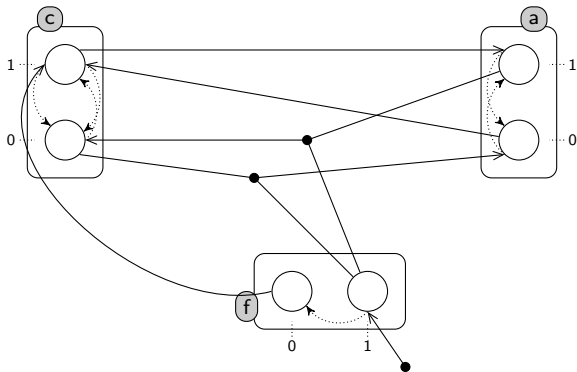


Asynchronous Automata Networks (AAN) Enriched Process Hitting (PH)



Asynchronous Automata Networks (AAN) Enriched Process Hitting (PH)

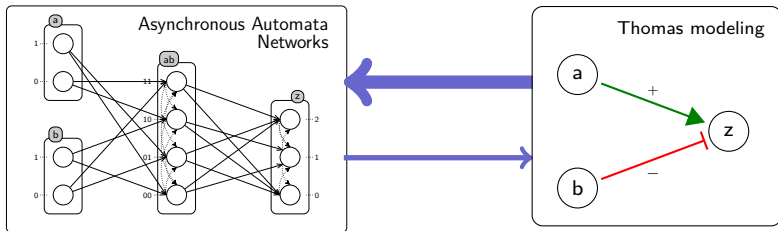
Model from [François *et al.*, *Molecular Systems Biology*, 2007]



Translations Between AAN and Thomas Modeling

[Folschette *et al.*, *Theoretical Computer Science*, 2015a]

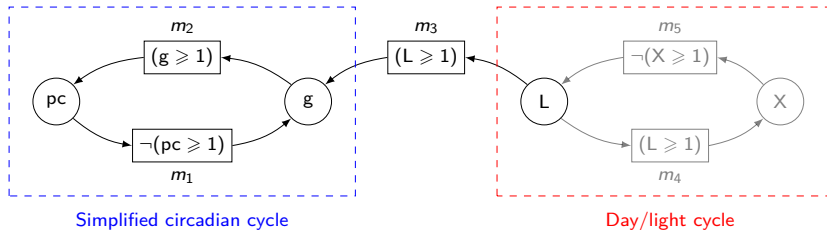
[Folschette *et al.*, *CS2Bio'13*, 2013]



- Asynchronous Automata Networks encompass Thomas modeling
- Mutual translations developed
- Results are also mutually applicable

Model Completion

A Simplified Circadian Cycle Model

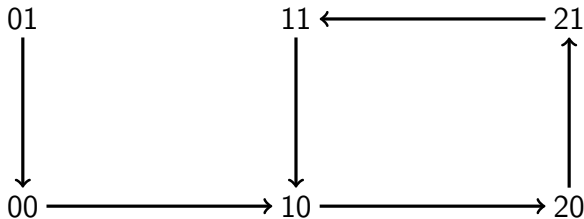
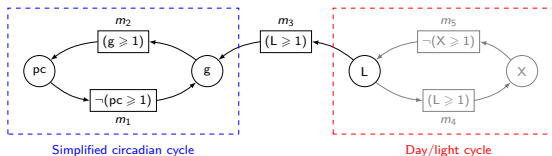


pc = PER/CRY complex
 g = *per* and *cry* genes

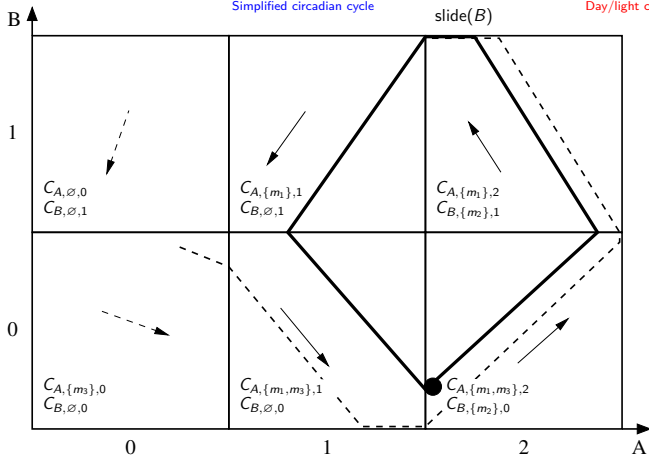
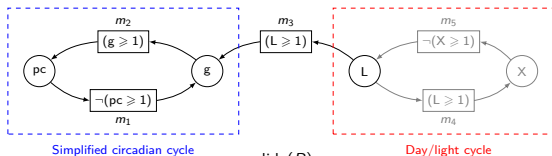
L = light of the day
 X = Modeling artifact (clock)

m_1 = PER/CRY complex inhibits *per* and *cry* genes
 m_2 = transcription and complexation
 m_3 = light makes BMAL1/CLOCK complex activate *per* and *cry* genes
 m_4 & m_5 = 12h day/night oscillation

Hybrid Thomas Modeling

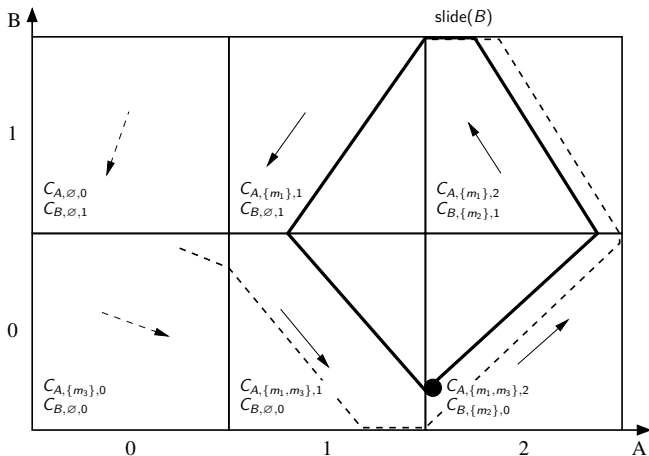


Hybrid Thomas Modeling



Hybrid Hoare Logic to Infer Parameters

$$\left\{ \begin{matrix} ??? \\ ??? \end{matrix} \right\} \left(\begin{matrix} T_4 \\ \top \\ B+ \end{matrix} \right); \left(\begin{matrix} T_3 \\ \text{slide}^+(B) \\ A- \end{matrix} \right); \left(\begin{matrix} T_2 \\ \top \\ B- \end{matrix} \right); \left(\begin{matrix} T_1 \\ \top \\ A+ \end{matrix} \right) \left\{ \begin{matrix} D_0 \equiv (\eta_A = 2 \wedge \eta_B = 0) \\ H_0 \equiv (\pi_{\text{initial}} = \pi_{\text{final}}) \end{matrix} \right\}$$

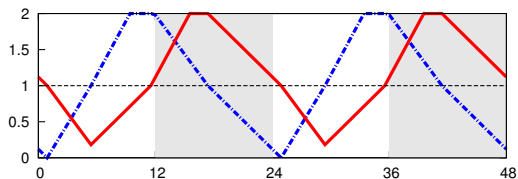


$$\begin{aligned}
& (((((((((\pi_g^{0'} = 0.12) \wedge ((\pi_{pc}^{0'} = 0.12) \wedge (\pi_L^{0'} = 0))) \wedge (((\pi_L^1 = 1) \wedge ((C_L, \{m5\}, 0 > 0) \wedge (\pi_L^1 = \\
& (\pi_L^1 - (C_L, \{m5\}, 0 \times 6.6)))))) \wedge (((\neg((C_g, \emptyset, 0 > 0) \wedge (\pi_g^{1'} > (\pi_g^1 - (C_g, \emptyset, 0 \times 6.6)))) \wedge (\neg((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{1'} < \\
& (\pi_{pc}^1 - (C_{pc}, \emptyset, 1 \times 6.6)))) \wedge (\neg((C_X, \emptyset, 0 > 0) \wedge (\pi_X^{1'} > (\pi_X^1 - (C_X, \emptyset, 0 \times 6.6)))))) \wedge (((\pi_L^1 = (1 - \pi_L^{0'})) \wedge ((\pi_g^1 = \pi_g^{0'}) \wedge \\
& ((\pi_{pc}^1 = \pi_{pc}^{0'}) \wedge (\pi_X^1 = \pi_X^{0'})))))) \wedge (((\pi_X^2 = 0) \wedge ((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{2'} = (\pi_X^2 - (C_X, \emptyset, 1 \times 0.6)))))) \wedge (((\neg((C_g, \emptyset, 0 > \\
& 0) \wedge (\pi_g^{2'} > (\pi_g^2 - (C_g, \emptyset, 0 \times 0.6)))) \wedge (\neg((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{2'} < (\pi_{pc}^2 - (C_{pc}, \emptyset, 1 \times 0.6)))) \wedge (\neg((C_L, \emptyset, 0 > \\
& 0) \wedge (\pi_L^{2'} > (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))))) \wedge (((\pi_L^2 = 0) \wedge ((C_L, \emptyset, 0 < 0) \Rightarrow (\pi_L^{2'} < (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))) \wedge ((\pi_X^2 = \\
& (1 - \pi_X^{1'})) \wedge ((\pi_g^2 = \pi_g^{1'}) \wedge ((\pi_{pc}^2 = \pi_{pc}^{1'}) \wedge (\pi_L^2 = \pi_L^{1'})))))) \wedge (((\pi_g^3 = 0) \wedge ((C_g, \emptyset, 1 < 0) \wedge (\pi_g^{3'} = \\
& (\pi_g^3 - (C_g, \emptyset, 1 \times 5.4)))) \wedge (\neg((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{3'} < (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge (\neg((C_L, \emptyset, 0 > 0) \wedge (\pi_L^{3'} > \\
& (\pi_L^3 - (C_L, \emptyset, 0 \times 5.4)))) \wedge (\neg((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{3'} < (\pi_X^3 - (C_X, \emptyset, 1 \times 5.4)))))) \wedge (((\pi_{pc}^3 = 1) \wedge ((C_{pc}, \{m2\}, 1 > \\
& 0) \Rightarrow (\pi_{pc}^{3'} > (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge ((\pi_g^3 = (1 - \pi_g^{2'})) \wedge ((\pi_{pc}^3 = \pi_{pc}^{2'}) \wedge ((\pi_L^3 = \pi_L^{2'}) \wedge (\pi_X^3 = \\
& \pi_X^{2'})))))) \wedge (((\pi_L^4 = 0) \wedge ((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{4'} = (\pi_L^4 - (C_L, \emptyset, 1 \times 0.47)))) \wedge (\neg((C_g, \{m3\}, 1 < 0) \wedge (\pi_g^{4'} < \\
& (\pi_g^4 - (C_g, \{m3\}, 1 \times 0.47)))) \wedge (\neg((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{4'} < (\pi_{pc}^4 - (C_{pc}, \{m2\}, 1 \times 0.47)))) \wedge (\neg((C_X, \{m4\}, 1 < \\
& 0) \wedge (\pi_X^{4'} < (\pi_X^4 - (C_X, \{m4\}, 1 \times 0.47)))))) \wedge ((\pi_L^4 = (1 - \pi_L^{3'})) \wedge ((\pi_g^4 = \pi_g^{3'}) \wedge ((\pi_{pc}^4 = \pi_{pc}^{3'}) \wedge (\pi_X^4 = \\
& \pi_X^{3'})))))) \wedge (((\pi_{pc}^5 = 1) \wedge ((C_{pc}, \{m2\}, 0 > 0) \wedge (\pi_{pc}^{5'} = (\pi_{pc}^5 - (C_{pc}, \{m2\}, 0 \times 5.53)))) \wedge (\neg((C_g, \{m1, m3\}, 1 < \\
& 0) \wedge (\pi_g^{5'} < (\pi_g^5 - (C_g, \{m1, m3\}, 1 \times 5.53)))) \wedge (\neg((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{5'} < (\pi_L^5 - (C_L, \emptyset, 1 \times 5.53)))) \wedge (\neg((C_X, \{m4\}, 1 < \\
& 0) \wedge (\pi_X^{5'} < (\pi_X^5 - (C_X, \{m4\}, 1 \times 5.53)))))) \wedge (((\pi_g^5 = 1) \wedge ((C_g, \{m1, m3\}, 1 > 0) \Rightarrow (\pi_g^{5'} > \\
& (\pi_g^5 - (C_g, \{m1, m3\}, 1 \times 5.53)))) \wedge ((\pi_{pc}^5 = (1 - \pi_{pc}^{4'})) \wedge ((\pi_g^5 = \pi_g^{4'}) \wedge ((\pi_L^5 = \pi_L^{4'}) \wedge (\pi_X^5 = \pi_X^{4'})))))) \wedge (((\pi_X^6 = \\
& 1) \wedge ((C_X, \{m4\}, 0 > 0) \wedge (\pi_X^{6'} = (\pi_X^6 - (C_X, \{m4\}, 0 \times 0.6)))) \wedge (\neg((C_g, \{m1, m3\}, 1 < 0) \wedge (\pi_g^{6'} < \\
& (\pi_g^6 - (C_g, \{m1, m3\}, 1 \times 0.6)))) \wedge (\neg((C_{pc}, \{m2\}, 0 > 0) \wedge (\pi_{pc}^{6'} > (\pi_{pc}^6 - (C_{pc}, \{m2\}, 0 \times 0.6)))) \wedge (\neg((C_L, \{m5\}, 1 < \\
& 0) \wedge (\pi_L^{6'} < (\pi_L^6 - (C_L, \{m5\}, 1 \times 0.6)))))) \wedge ((\pi_X^6 = (1 - \pi_X^{5'})) \wedge ((\pi_g^6 = \pi_g^{5'}) \wedge ((\pi_{pc}^6 = \pi_{pc}^{5'}) \wedge (\pi_L^6 = \\
& \pi_L^{5'})))))) \wedge (((\pi_g^7 = 1) \wedge ((C_g, \{m1, m3\}, 0 > 0) \wedge (\pi_g^{7'} = (\pi_g^7 - (C_g, \{m1, m3\}, 0 \times 4.5)))) \wedge (\neg((C_{pc}, \emptyset, 0 > \\
& 0) \wedge (\pi_{pc}^{7'} > (\pi_{pc}^7 - (C_{pc}, \emptyset, 0 \times 4.5)))) \wedge (\neg((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{7'} < (\pi_L^7 - (C_L, \{m5\}, 1 \times 4.5)))) \wedge (\neg((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{7'} > (\pi_X^7 - (C_X, \{m4\}, 0 \times 4.5)))))) \wedge ((\pi_g^7 = (1 - \pi_g^{6'})) \wedge ((\pi_{pc}^7 = \pi_{pc}^{6'}) \wedge ((\pi_L^7 = \pi_L^{6'}) \wedge (\pi_X^7 = \\
& \pi_X^{6'})))))) \wedge (((\pi_{pc}^8 = 0) \wedge ((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{8'} = (\pi_{pc}^8 - (C_{pc}, \emptyset, 1 \times 0.9)))) \wedge (\neg((C_g, \{m3\}, 0 > 0) \wedge (\pi_g^{8'} > \\
& (\pi_g^8 - (C_g, \{m3\}, 0 \times 0.9)))) \wedge (\neg((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{8'} < (\pi_L^8 - (C_L, \{m5\}, 1 \times 0.9)))) \wedge (\neg((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{8'} > (\pi_X^8 - (C_X, \{m4\}, 0 \times 0.9)))))) \wedge ((\pi_{pc}^8 = (1 - \pi_{pc}^{7'})) \wedge ((\pi_g^8 = \pi_g^{7'}) \wedge ((\pi_L^8 = \pi_L^{7'}) \wedge (\pi_X^8 = \pi_X^{7'}))))))
\end{aligned}$$

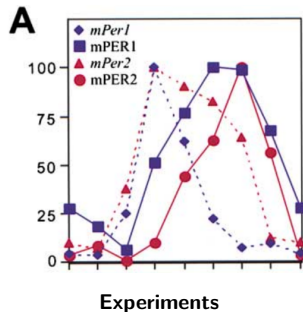
$$\begin{aligned}
& (((((((((\pi_g^{0'} = 0.12) \wedge ((\pi_{pc}^{0'} = 0.12) \wedge (\pi_L^{0'} = 0))) \wedge (((\pi_L^1 = 1) \wedge ((C_L, \{m5\}, 0 > 0) \wedge (\pi_L^1 = \\
& (\pi_L^1 - (C_L, \{m5\}, 0 \times 6.6)))))) \wedge (((((C_g, \emptyset, 0 > 0) \wedge (\pi_g^{1'} > (\pi_g^1 - (C_g, \emptyset, 0 \times 6.6)))) \wedge (((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{1'} < \\
& (\pi_{pc}^1 - (C_{pc}, \emptyset, 1 \times 6.6)))) \wedge (((((C_X, \emptyset, 0 > 0) \wedge (\pi_X^{1'} > (\pi_X^1 - (C_X, \emptyset, 0 \times 6.6)))))) \wedge (((\pi_L^1 = (1 - \pi_L^{0'})) \wedge ((\pi_g^1 = \pi_g^{0'})) \wedge \\
& ((\pi_{pc}^1 = \pi_{pc}^{0'}) \wedge (\pi_X^1 = \pi_X^{0'})))))) \wedge (((((\pi_X^2 = 0) \wedge ((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{2'} = (\pi_X^2 - (C_X, \emptyset, 1 \times 0.6)))))) \wedge (((((C_g, \emptyset, 0 > \\
& 0) \wedge (\pi_g^{2'} > (\pi_g^2 - (C_g, \emptyset, 0 \times 0.6)))) \wedge (((((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{2'} < (\pi_{pc}^2 - (C_{pc}, \emptyset, 1 \times 0.6)))) \wedge (((C_L, \emptyset, 0 > \\
& 0) \wedge (\pi_L^{2'} > (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))))) \wedge (((((\pi_L^2 = 0) \wedge ((C_L, \emptyset, 0 < 0) \Rightarrow (\pi_L^{2'} < (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))) \wedge (((\pi_X^2 = \\
& (1 - \pi_X^{1'})) \wedge ((\pi_g^2 = \pi_g^{1'})) \wedge ((\pi_{pc}^2 = \pi_{pc}^{1'}) \wedge (\pi_L^2 = \pi_L^{1'})))))) \wedge (((((\pi_g^3 = 0) \wedge ((C_g, \emptyset, 1 < 0) \wedge (\pi_g^{3'} = \\
& (\pi_g^3 - (C_g, \emptyset, 1 \times 5.4)))) \wedge (((((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{3'} < (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge (((C_L, \emptyset, 0 > 0) \wedge (\pi_L^{3'} > \\
& (\pi_L^3 - (C_L, \emptyset, 0 \times 5.4)))) \wedge (((((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{3'} < (\pi_X^3 - (C_X, \emptyset, 1 \times 5.4)))) \wedge (((((\pi_{pc}^3 = 1) \wedge ((C_{pc}, \{m2\}, 1 > \\
& 0) \Rightarrow (\pi_{pc}^{3'} > (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge ((((\pi_g^3 = (1 - \pi_g^{2'})) \wedge ((\pi_{pc}^3 = \pi_{pc}^{2'}) \wedge ((\pi_L^3 = \pi_L^{2'}) \wedge (\pi_X^3 = \\
& \pi_X^{2'})))))) \wedge (((((\pi_L^4 = 0) \wedge ((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{4'} = (\pi_L^4 - (C_L, \emptyset, 1 \times 0.6)))) \wedge (((((C_g, \{m3\}, 1 < 0) \wedge (\pi_g^{4'} < \\
& (\pi_g^4 - (C_g, \{m3\}, 1 \times 0.47)))) \wedge (((((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{4'} < (\pi_{pc}^4 - (C_{pc}, \{m2\}, 1 \times 0.47)))) \wedge (((C_X, \{m4\}, 1 < \\
& 0) \wedge (\pi_X^{4'} < (\pi_X^4 - (C_X, \{m4\}, 1 \times 0.47)))))) \wedge (((((\pi_L^4 = (1 - \pi_L^{3'})) \wedge ((\pi_g^4 = \pi_g^{3'}) \wedge ((\pi_{pc}^4 = \pi_{pc}^{3'}) \wedge (\pi_X^4 = \\
& \pi_X^{3'})))))) \wedge (((((\pi_{pc}^5 = 1) \wedge ((C_{pc}, \{m2\}, 0 > 0) \wedge (\pi_{pc}^{5'} = (\pi_{pc}^5 - (C_{pc}, \{m2\}, 0 \times 5.53)))) \wedge (((((C_g, \{m1, m3\}, 1 < \\
& 0) \wedge (\pi_g^{5'} < (\pi_g^5 - (C_g, \{m1, m3\}, 1 \times 5.53)))) \wedge (((((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{5'} < (\pi_L^5 - (C_L, \emptyset, 1 \times 5.53)))) \wedge (((C_X, \{m4\}, 1 < \\
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& 1) \wedge ((C_X, \{m4\}, 0 > 0) \wedge (\pi_X^{6'} = (\pi_X^6 - (C_X, \{m4\}, 0 \times 0.6)))) \wedge (((((C_g, \{m1, m3\}, 1 < 0) \wedge (\pi_g^{6'} < \\
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& 0) \wedge (\pi_L^{6'} < (\pi_L^6 - (C_L, \{m5\}, 1 \times 0.6)))))) \wedge ((((\pi_X^6 = (1 - \pi_X^{5'})) \wedge ((\pi_g^6 = \pi_g^{5'}) \wedge ((\pi_{pc}^6 = \pi_{pc}^{5'}) \wedge (\pi_L^6 = \\
& \pi_L^{5'})))))) \wedge (((((\pi_g^7 = 1) \wedge ((C_g, \{m1, m3\}, 0 > 0) \wedge (\pi_g^{7'} = (\pi_g^7 - (C_g, \{m1, m3\}, 0 \times 4.5)))) \wedge (((((C_{pc}, \emptyset, 0 > \\
& 0) \wedge (\pi_{pc}^{7'} > (\pi_{pc}^7 - (C_{pc}, \emptyset, 0 \times 4.5)))) \wedge (((((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{7'} < (\pi_L^7 - (C_L, \{m5\}, 1 \times 4.5)))) \wedge (((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{7'} > (\pi_X^7 - (C_X, \{m4\}, 0 \times 4.5)))))) \wedge (((((\pi_g^7 = (1 - \pi_g^{6'})) \wedge ((\pi_{pc}^7 = \pi_{pc}^{6'}) \wedge ((\pi_L^7 = \pi_L^{6'}) \wedge (\pi_X^7 = \\
& \pi_X^{6'})))))) \wedge (((((\pi_{pc}^8 = 0) \wedge ((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{8'} = (\pi_{pc}^8 - (C_{pc}, \emptyset, 1 \times 0.9)))) \wedge (((((C_g, \{m3\}, 0 > 0) \wedge (\pi_g^{8'} > \\
& (\pi_g^8 - (C_g, \{m3\}, 0 \times 0.9)))) \wedge (((((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{8'} < (\pi_L^8 - (C_L, \{m5\}, 1 \times 0.9)))) \wedge (((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{8'} > (\pi_X^8 - (C_X, \{m4\}, 0 \times 0.9)))))) \wedge ((((\pi_{pc}^8 = (1 - \pi_{pc}^{7'})) \wedge ((\pi_g^8 = \pi_g^{7'}) \wedge ((\pi_L^8 = \pi_L^{7'}) \wedge (\pi_X^8 = \pi_X^{7'}))))))
\end{aligned}$$

Results

- **Simplifications** of the constraints
- Let's use a **solver!** :-)
- Results checked with a simulation:



Simulation with compatible values

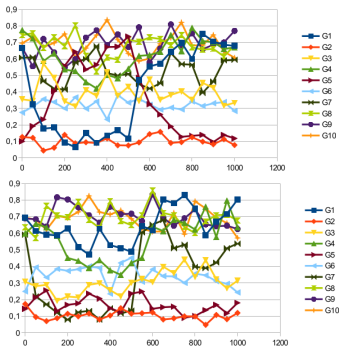


Modeling Gene Interactions

Goal: understand biological dynamics, i.e. gene interactions.

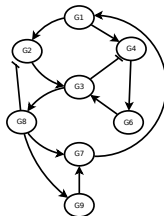
Data: time series

- discrete/regular time steps
- continuous value



Model: Boolean network

- discrete/regular time steps
- discrete values



Modeling Gene Interactions

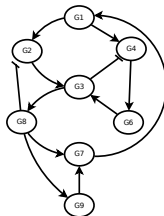
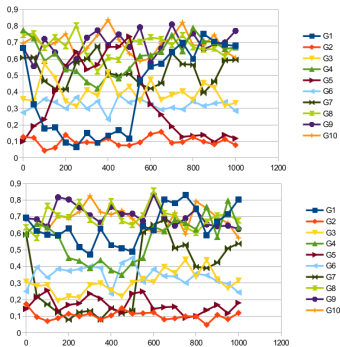
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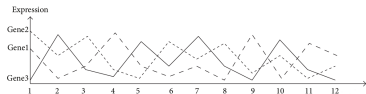
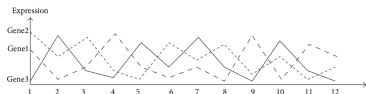
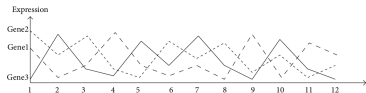
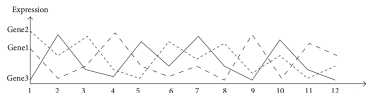
Model: Boolean network

- discrete/regular time steps
- discrete values



Continuum Logic Program

INPUT:
A set of **time series data**

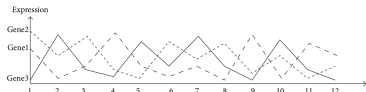
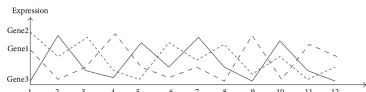
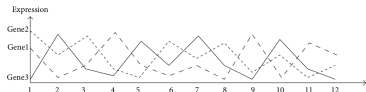
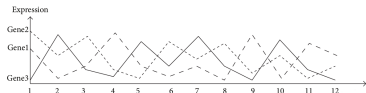


OUTPUT:
A **continuum** logic program

$$\begin{aligned}
 p([0, 0.5], t) &\leftarrow q([0, 0.5], t - 1). \\
 p([0.5, 1], t) &\leftarrow q([0.5, 1], t - 1). \\
 q([0, 0.5], t) &\leftarrow p([0, 0.5], t - 1) \wedge r([0.5, 1], t - 1). \\
 q([0.5, 1], t) &\leftarrow p([0.5, 1], t - 1) \wedge r([0.5, 1], t - 1). \\
 r([0, 0.5], t) &\leftarrow p([0.5, 1], t - 1). \\
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 \end{aligned}$$

Continuum Logic Program

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A set of **time series data**

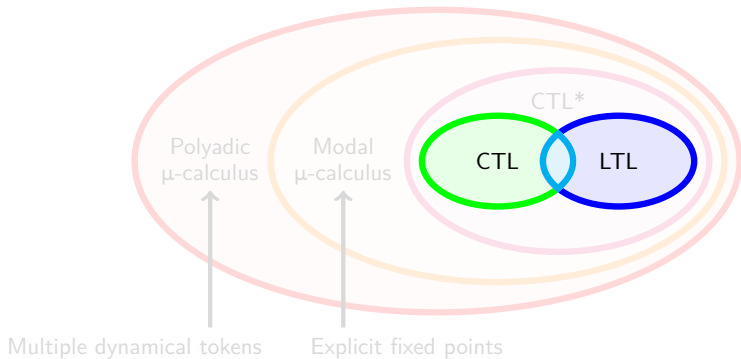


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Dynamic Analysis

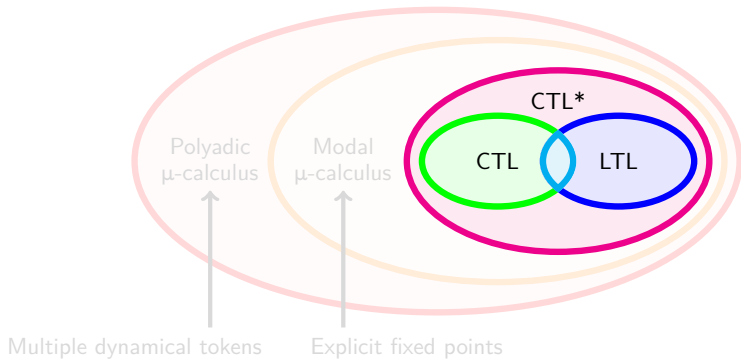
Polyadic μ -calculus



Aim: Unification of properties without quantifiers

- Enumeration of attractors & disruptions
- Bisimulation between two models (regarding some observables)
- Searching Zeno behaviors

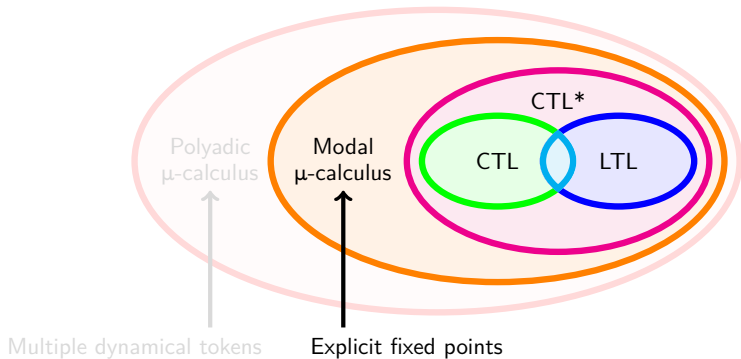
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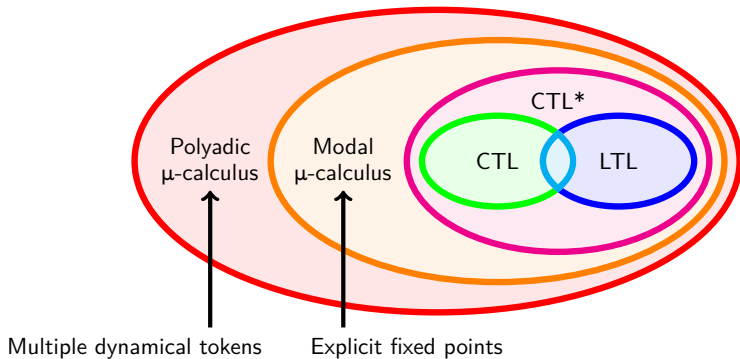
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Polyadic μ -calculus



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Answer Set Programming

Answer Set Programming (ASP): Declarative & logic programming

Rule: $head \leftarrow body.$

“If $body$ is true, then $head$ must be true (usual logical consequence)”

Fact: $head.$

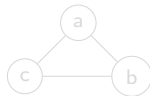
“ $head$ is always true”

Constraint: $\perp \leftarrow body.$

“If $body$ is true, it invalidates the whole answer set”

Example:

$node(a). node(b). node(c).$
 $edge(a, b). edge(b, c). edge(a, c).$
 $edge(X, Y) \leftarrow edge(Y, X).$



Solving: Finding the minimal set of atoms satisfying the problem

$node(a) node(c) node(b)$
 $edge(a, b) edge(b, c) edge(a, c)$
 $edge(b, a) edge(c, b) edge(c, a)$

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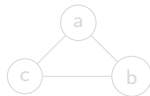
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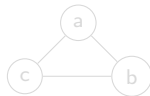
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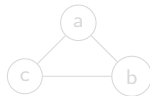
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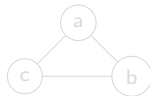
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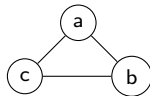
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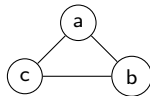
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Answer Set Programming

Cardinalities: $\min \{ atom : enum \} \max \leftarrow body.$

- Enumerates all atoms of the form *atom* according to the variables of *enum*
- Keep between *min* and *max* possibilities
- Creates as many answer sets as there are combinations

General method:

1) Enumerate of all candidate combinations using cardinalities

color(red). color(green). color(blue).

$1 \{ attrib(X, C) : color(C) \} 1 \leftarrow node(X).$

Answer set 1: *attrib(b,red) attrib(c,red) attrib(a,red)*

Answer set 2: *attrib(b,red) attrib(c,red) attrib(a,blue)*

Answer set 3: *attrib(b,red) attrib(c,green) attrib(a,blue)*

⋮
 ⋮ (27 answer sets)

2) Filter out the undesired candidates using constraints

$\perp \leftarrow attrib(X, C), attrib(Y, C), edge(X, Y).$

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Conclusion on ASP for Model-checking

[Ben Abdallah, Folschette, Roux, Magnin, *BIBM'15*, 2015]

[Ben Abdallah, Folschette, Roux, Magnin, *AMB*, 2017]

- **General approach applied to dynamical analysis:**

- 1) Describe the model with facts and rules (automata, actions, dynamics)
- 2) Enumerate all states/all dynamics with cardinalities
- 3) Filter out unwanted results

- Applications: **Stable states**, **Reachability** analysis, **Attractors** enumeration

- **Pros:** Very flexible (programming language) & Complexity handled by the solver

- **Cons:** Iterative approach (requires to cap the search) & Still computational

Models		Stable states	Reachability analysis		
Name	States	ASP	libddd ¹	GINsim ²	ASP
egfr20	2 ⁶⁴	0.017s	1min 55s	2min 32s	12s
tcrsig40	2 ⁷³	0.021s	∞	∞	4min 28s

¹ LIP6/Move [Couvreur *et al.*, *Lecture Notes in Computer Science*, 2002]

² TAGC/IGC [Chaouiya, Naldi, Thieffry, *Methods in Molecular Biology*, 2012]

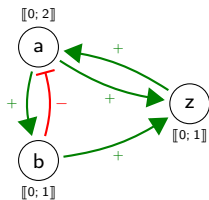
egfr20 : Epithelial Growth Factor Receptor (20 components) [Sahin *et al.*, 2009]

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Static Analysis of Thomas Modeling

[Thomas, *Numerical Methods in the Study of Critical Phenomena*, 1981]

Conjectures of René Thomas:

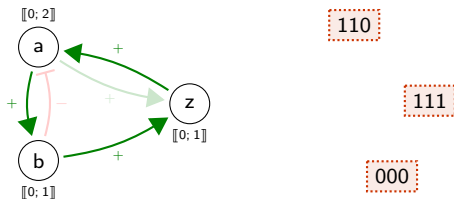


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Conjectures of René Thomas:

- Multiple **stable states** \Rightarrow positive cycle in the graph

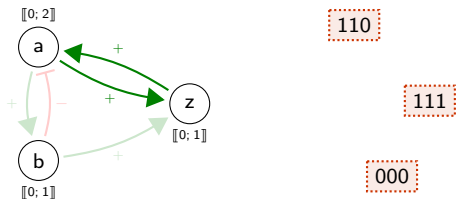


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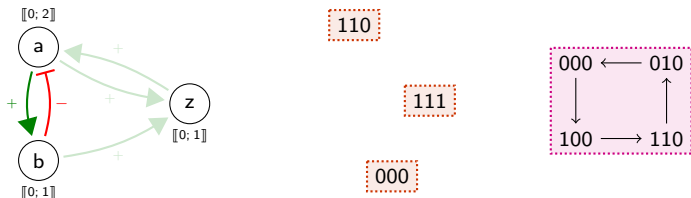


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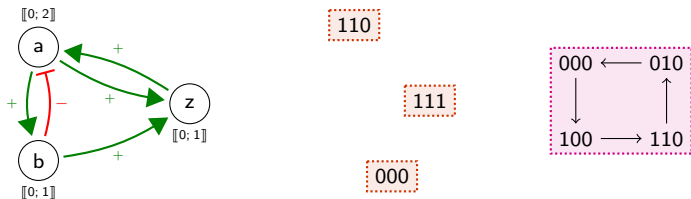


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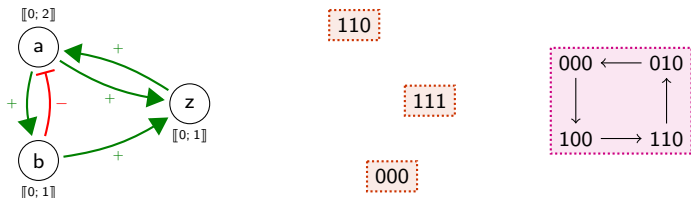
Proofs: [Remy, Ruet & Thieffry, *Advances in Applied Mathematics*, 2008]
 [Richard, *Advances in Applied Mathematics*, 2010]
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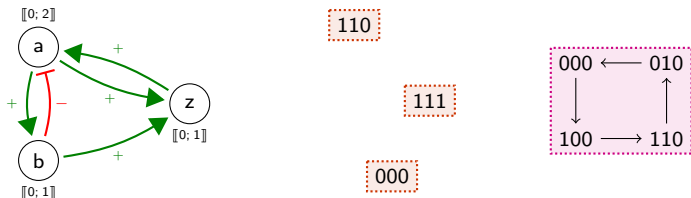
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No negative cycle in the graph \Rightarrow **No complex attractor (only stable states)**

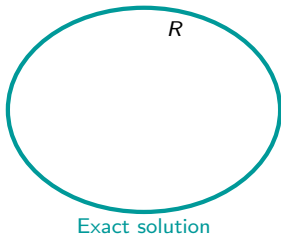


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Over- and Under-approximations

[Paulevé *et al.*, *Mathematical Structures in Computer Science*, 2012]

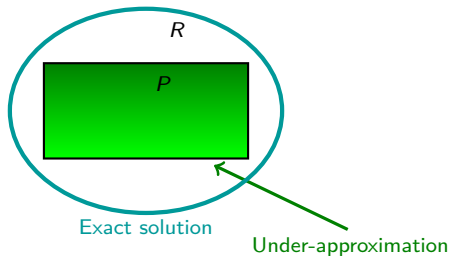
- Directly checking R is hard (**exponential**)
- Rather check **approximations** P and Q so that: $P \Rightarrow R \Rightarrow Q$
Computing P or Q is much simpler (roughly **polynomial**)



Over- and Under-approximations

[Paulevé *et al.*, *Mathematical Structures in Computer Science*, 2012]

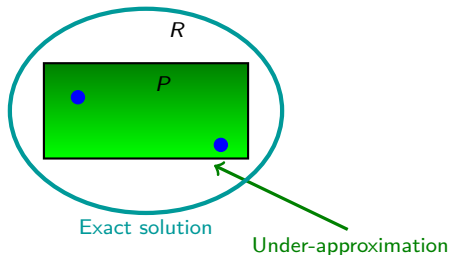
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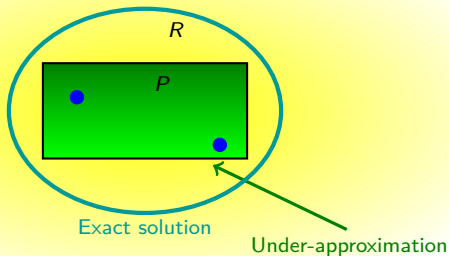
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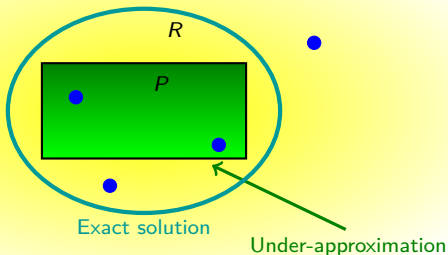
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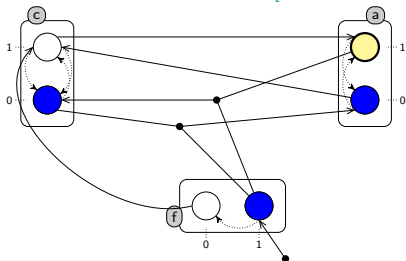
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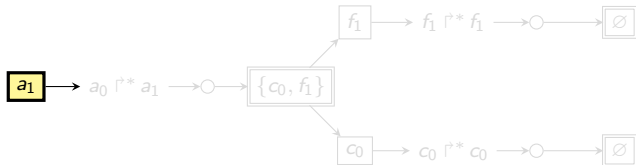


Abstract Interpretation (Under-approximation)

[Folschette et al., *Theoretical Computer Science*, 2015b]



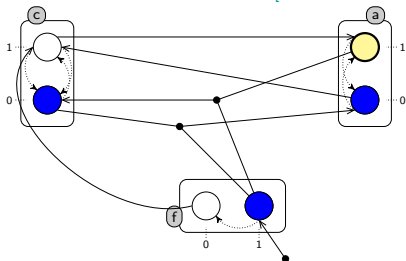
- No cycle
- No conflict
- All leaves are \emptyset



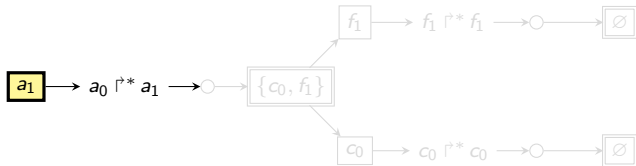
OK! :-) scenario = $\{c_0, f_1\} \rightarrow a_0 \uparrow a_1$

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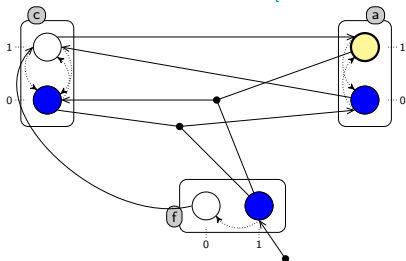
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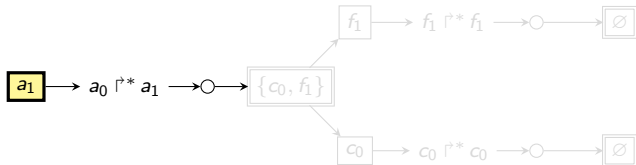
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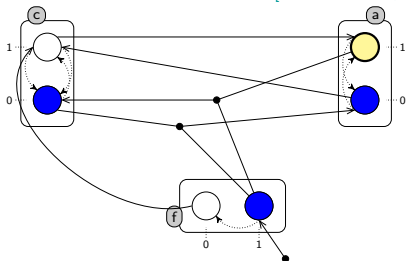
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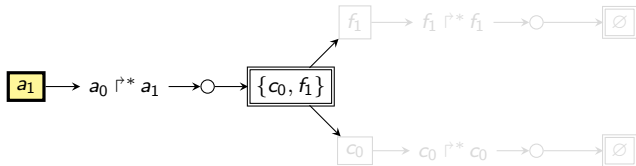
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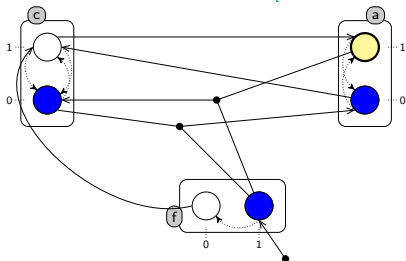
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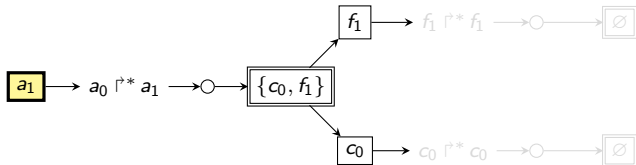
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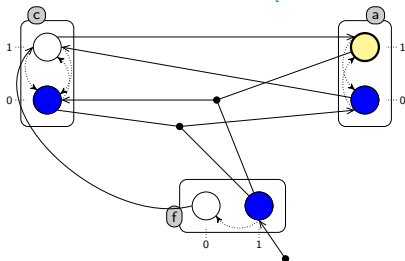
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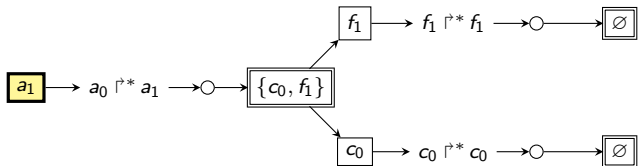
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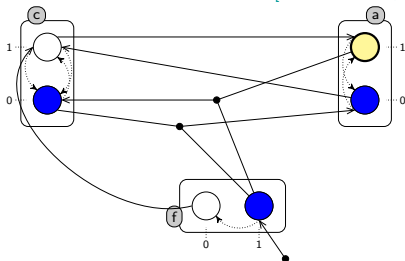
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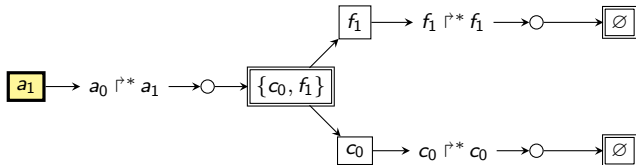
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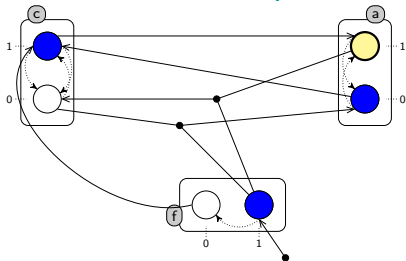
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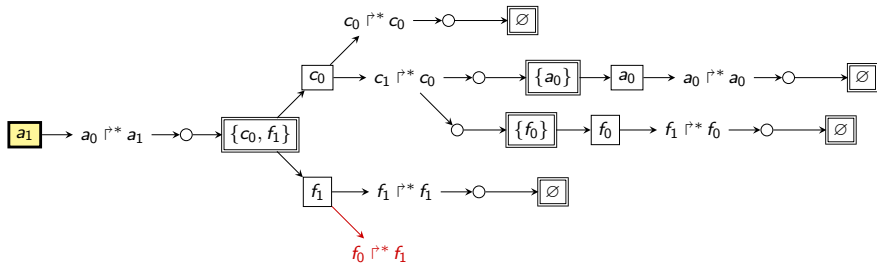
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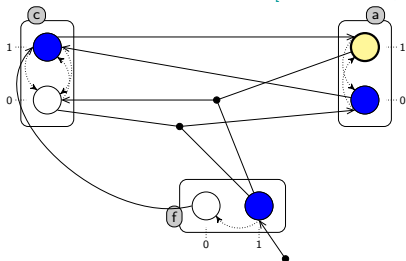
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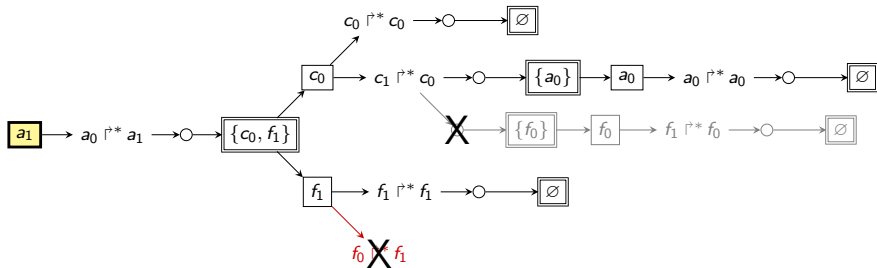
Cannot conclude... :-|

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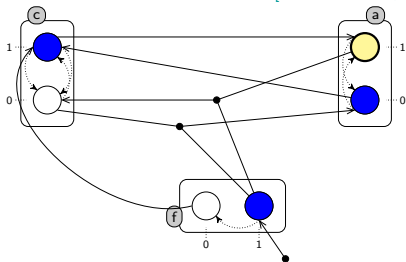
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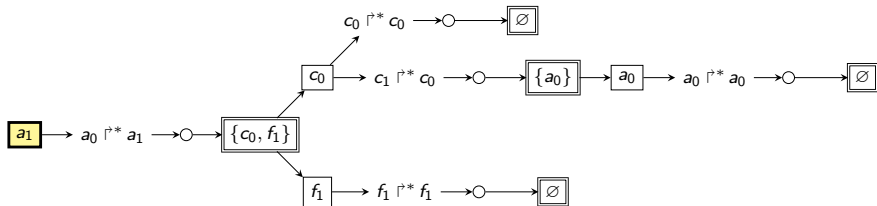
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OK! :-) $\{a_0\} \rightarrow c_1 \uparrow^* c_0 :: \{c_0, f_1\} \rightarrow a_0 \uparrow^* a_1$

Implementation of the Abstract Interpretation

Complexity:

- Computation of the local causality graph:
 - Polynomial in the number of automata
 - Exponential in the number of local states of each automata (usually very low, max. 4)
- Analysis of the graph (sufficient condition):
 - Polynomial in the size of the abstract graph
- Enumeration of the subsets of solutions (if needed):
 - Exponential in the size of the abstract graph

→ Very efficient on biological networks: **many components with few local states**

Model	Automata	Actions	States	libddd ¹	GINsim ²	PINT ³
egfr20	35	670	2 ⁶⁴		<1s	0.02s
tcrsig40	54	301	2 ⁷³		∞	0.02s
tcrsig94	133	1124	2 ¹⁹⁴	[>1min - ∞]		0.03s
egfr104	193	2356	2 ³²⁰	[>1min - ∞]		0.16s

¹ LIP6/Move [Couvreur *et al.*, *Lecture Notes in Computer Science*, 2002]

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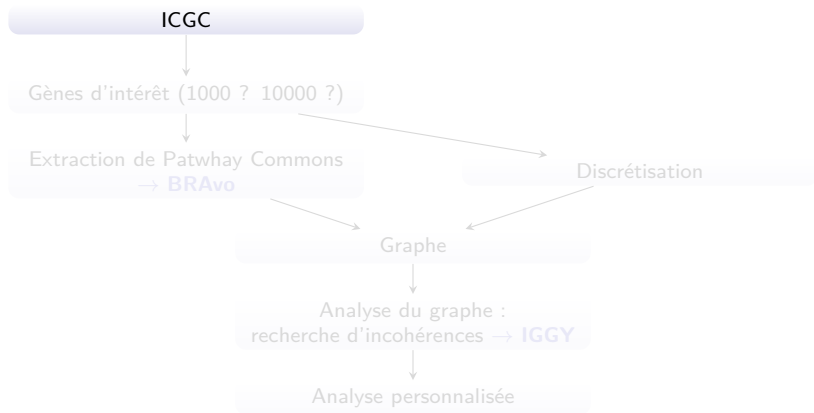
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Ongoing Work

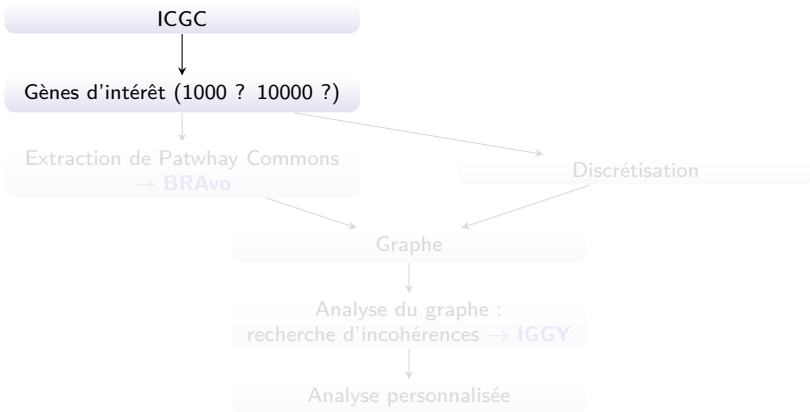
TGF- β Pathways Project

« Modélisation des réseaux d'influence du TGF- β lors de la progression tumorale pour l'identification de cibles thérapeutiques »



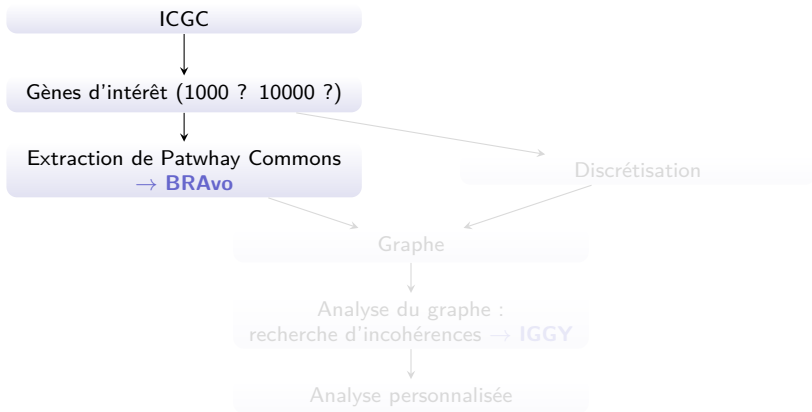
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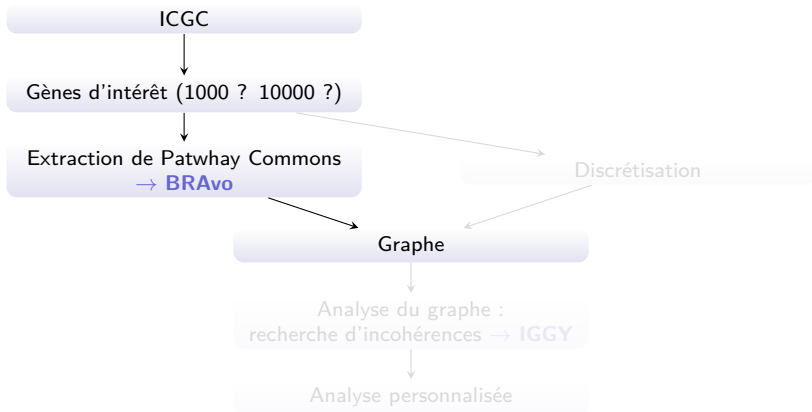
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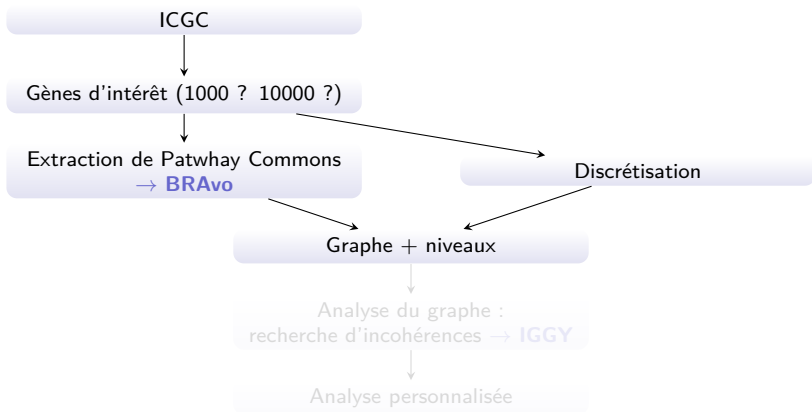
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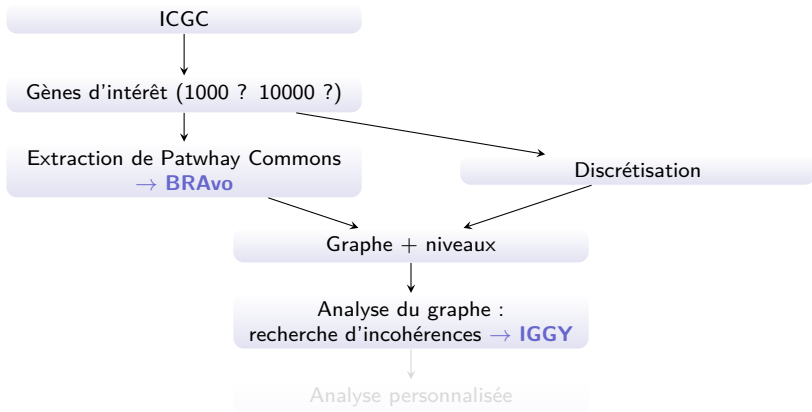
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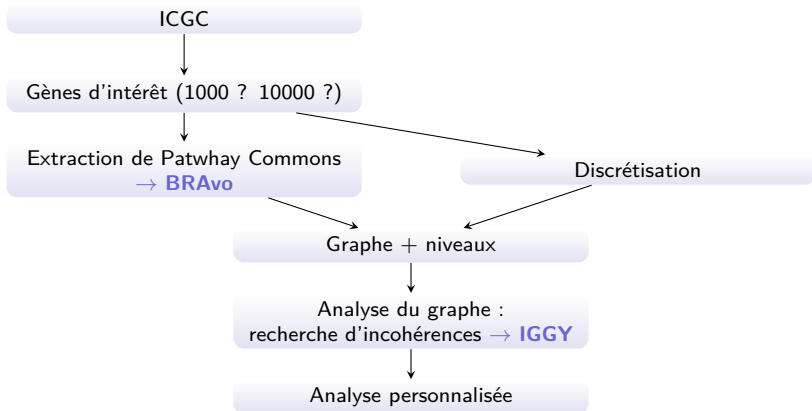
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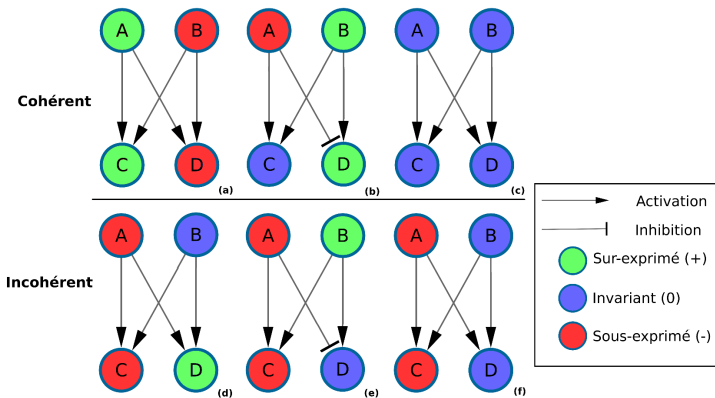
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Inconsistency Search With Coloring

- Some **observations** from experiments give an initial coloring
- **Propagate** the coloring to neighbor nodes
- Minimize **inconsistencies**
- Minimize the **repairs** to fix the inconsistencies



Summary

Frameworks: modeling biological processes

- **Thomas modeling** (historically widespread)
- **Asynchronous Automata Networks** (generalization)
- **Hybrid Thomas modeling** (generalization)

Model completion: inferring missing information on the model

- **Hybrid Hoare logic** (parameters/logical gates on Hybrid Thomas modeling)
- **Continuous transitions** (logical thresholds from expression profiles)

Dynamic analyses: explore the dynamics of a model

- **μ -calculus & Answer Set Programming** (exhaustive)
- **Abstract interpretation** (approximations)

TGF- β pathways project: my work here as a postdoc

- Extract and build a big graph from databases
- Search for inconsistencies in cancerous types

Collaborations



Olivier ROUX



Morgan MAGNIN



Emna BEN ABDALLAH



Tony RIBEIRO



Katsumi INOUE



Martin LANGE



Loïc PAULEVÉ



Jean-Paul COMET



Jonathan BEHAEGEL

Bibliography

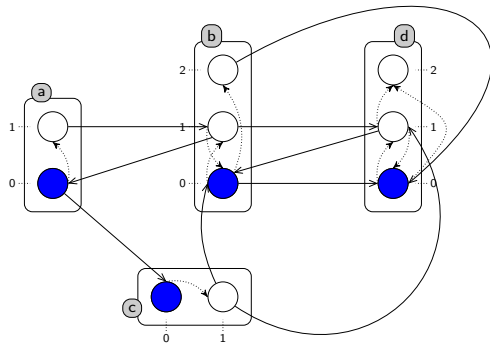
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- Emna Ben Abdallah, **Maxime Folschette**, Olivier Roux, Morgan Magnin. [Exhaustive analysis of dynamical properties of Biological Regulatory Networks with Answer Set Programming](#), *IEEE International Conference on Bioinformatics and Biomedicine (BIBM'15)*, 281–285, IEEE. November 2015.
- Emna Ben Abdallah, **Maxime Folschette**, Olivier Roux, Morgan Magnin. [ASP-based method for the enumeration of attractors in non-deterministic synchronous and asynchronous multi-valued networks](#), *Algorithms for Molecular Biology*, series *Constraints in Bioinformatics*, Accepted in July 2017, in edition.
- Tony Ribeiro, Sophie Tourret, **Maxime Folschette**, Morgan Magnin, Domenico Borzacchiello, Francisco Chinesta, Olivier Roux, Katsumi Inoue. [Learning Programs with Continuous Domains from State Transitions](#), *The 27th International Conference on Inductive Logic Programming (ILP 2017)*. September 2017.
- Jonathan Behaegel, Jean-Paul Comet, **Maxime Folschette**. [Constraint Identification Using Modified Hoare Logic on Hybrid Models of Gene Networks](#), *International Symposium on Temporal Representation and Reasoning (TIME)*. October 2017.

The Reachability Problem

[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]

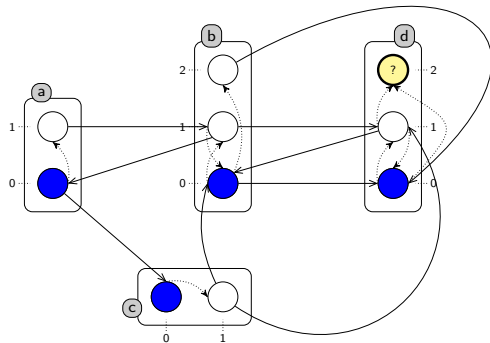


- Initial state

$\langle a_1, b_0, c_0, d_0 \rangle$

The Reachability Problem

[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]



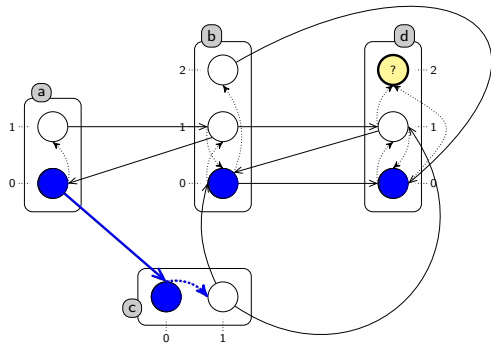
- Initial state

$\langle a_1, b_0, c_0, d_0 \rangle$

- Objective

$[d_2]$

The Reachability Problem

[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]

- Initial state

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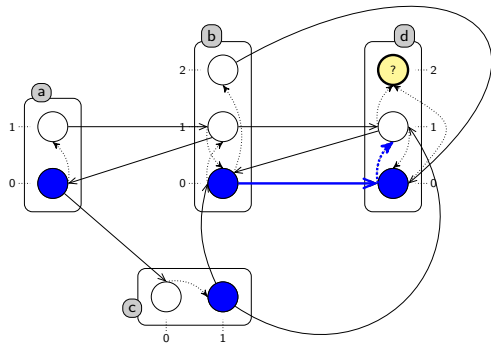
- Objective

 $[d_2]$

→ Concretization of the objective = scenario

$$\underline{a_0 \rightarrow c_0 \uparrow c_1} :: b_0 \rightarrow d_0 \uparrow d_1 :: c_1 \rightarrow b_0 \uparrow b_1 :: b_1 \rightarrow d_1 \uparrow d_2$$

The Reachability Problem

[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]

- Initial state
- Objective

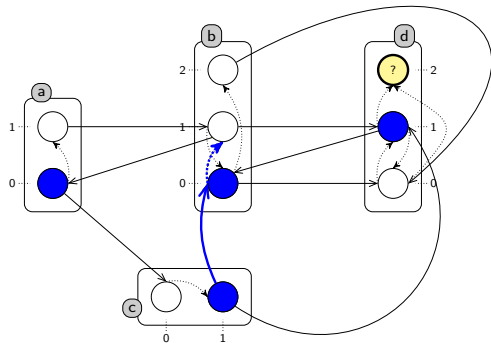
 $\langle a_1, b_0, c_0, d_0 \rangle$ $[d_2]$

→ Concretization of the objective = scenario

$$a_0 \rightarrow c_0 \uparrow c_1 :: \underline{b_0 \rightarrow d_0 \uparrow d_1} :: c_1 \rightarrow b_0 \uparrow b_1 :: b_1 \rightarrow d_1 \uparrow d_2$$

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[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]



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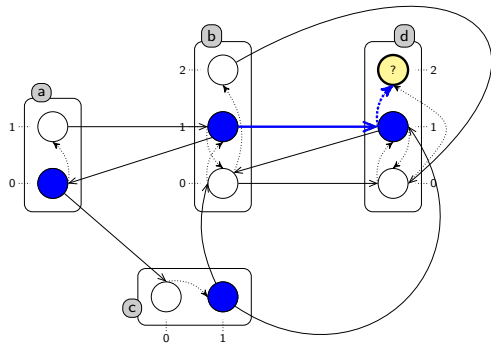
$\langle a_1, b_0, c_0, d_0 \rangle$

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→ Concretization of the objective = scenario

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[Paulevé et al., *Mathematical Structures in Computer Science*, 2012]

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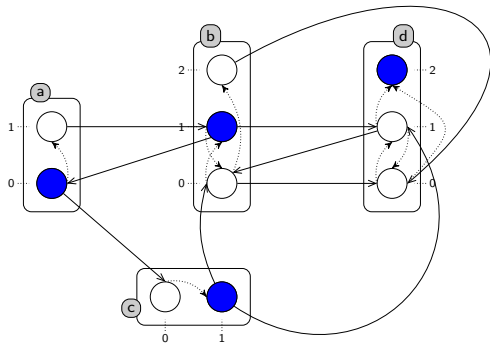
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 $[d_2]$

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$$a_0 \rightarrow c_0 \uparrow c_1 :: b_0 \rightarrow d_0 \uparrow d_1 :: c_1 \rightarrow b_0 \uparrow b_1 :: \underline{b_1 \rightarrow d_1 \uparrow d_2}$$

The Reachability Problem

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- Objective

 $[d_2]$

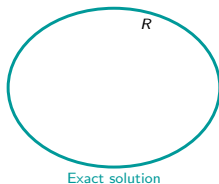
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$$a_0 \rightarrow c_0 \uparrow c_1 :: b_0 \rightarrow d_0 \uparrow d_1 :: c_1 \rightarrow b_0 \uparrow b_1 :: b_1 \rightarrow d_1 \uparrow d_2$$

Over- and Under-approximations

[Paulevé *et al.*, *Mathematical Structures in Computer Science*, 2012]

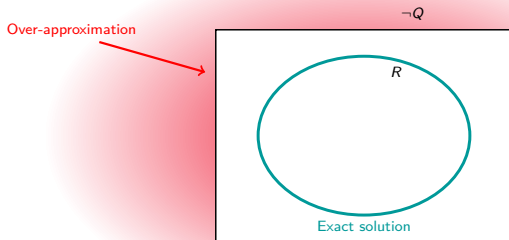
- Directly checking R is hard (**exponential**)
- Rather check **approximations** P and Q so that: $P \Rightarrow R \Rightarrow Q$
Computing P or Q is much simpler (roughly **polynomial**)



Over- and Under-approximations

[Paulevé *et al.*, *Mathematical Structures in Computer Science*, 2012]

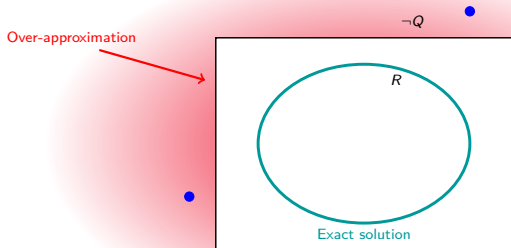
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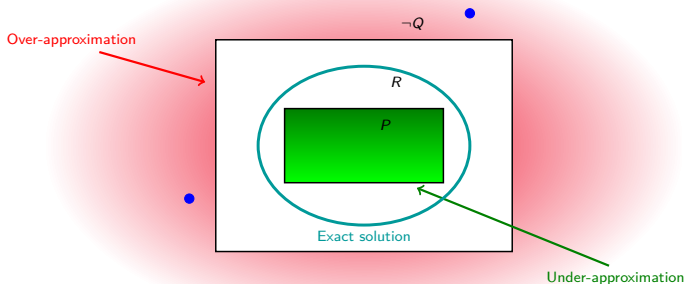
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Over- and Under-approximations

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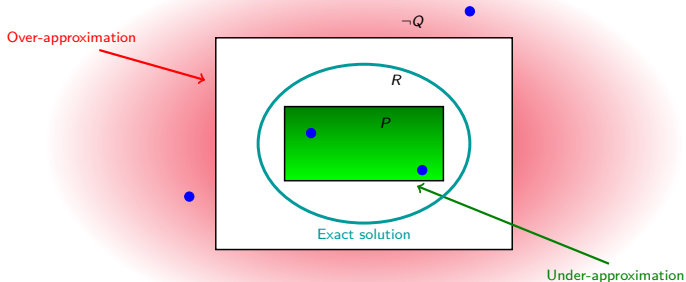
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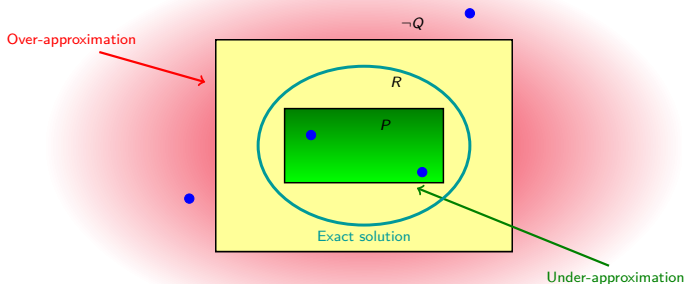
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Over- and Under-approximations

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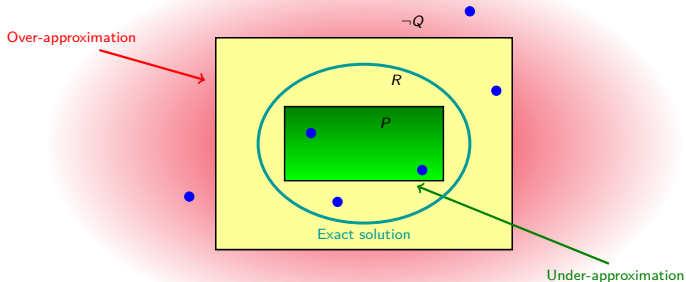
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Over- and Under-approximations

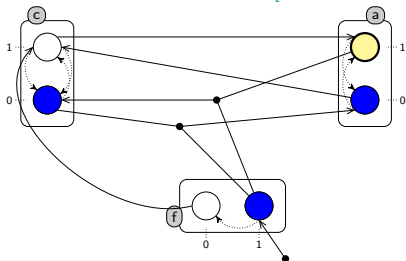
[Paulevé *et al.*, *Mathematical Structures in Computer Science*, 2012]

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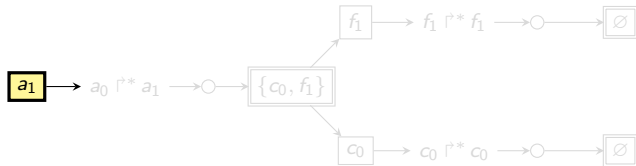


Abstract Interpretation (Under-approximation)

[Folschette et al., *Theoretical Computer Science*, 2015b]



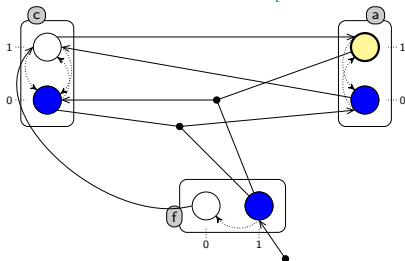
- No conflict
- All leaves are \emptyset



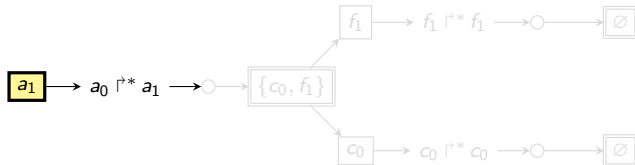
$$\{c_0, f_1\} \rightarrow a_0 \dot{r} a_1$$

Abstract Interpretation (Under-approximation)

[Folschette et al., *Theoretical Computer Science*, 2015b]



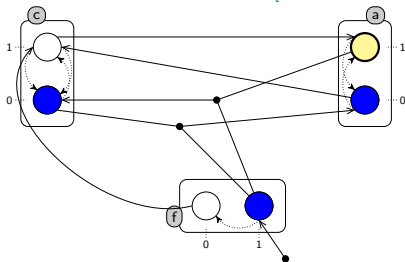
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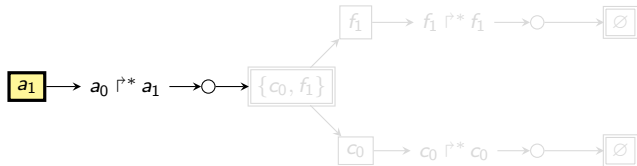
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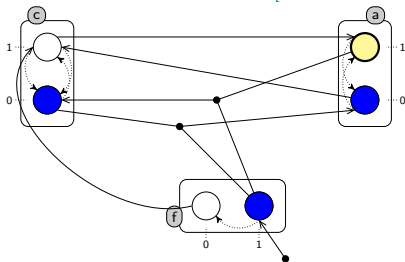
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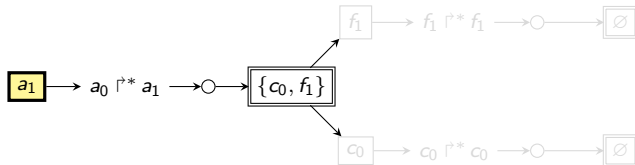
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Abstract Interpretation (Under-approximation)

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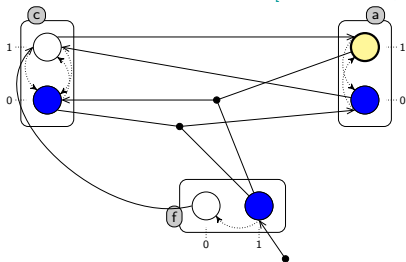
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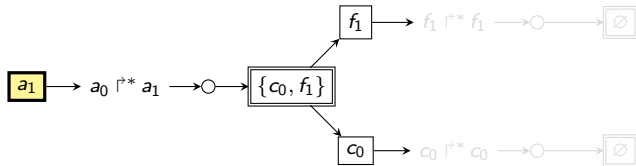
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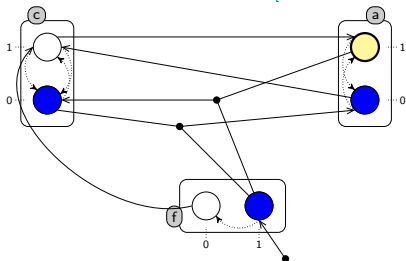
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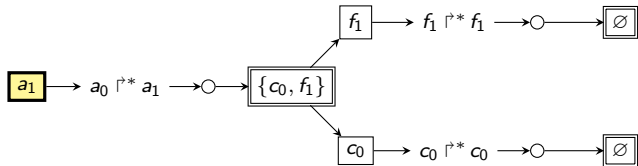
$$\{c_0, f_1\} \rightarrow a_0 \dot{r}^* a_1$$

Abstract Interpretation (Under-approximation)

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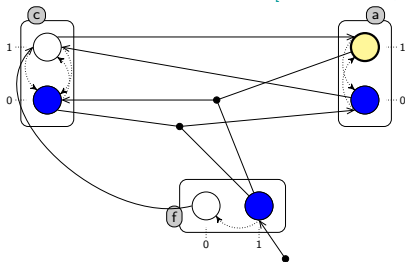
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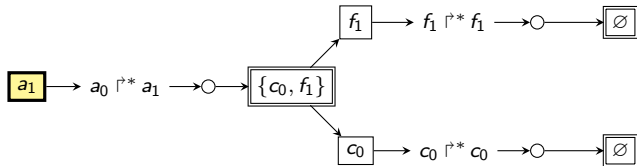
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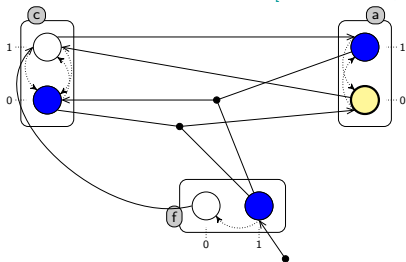
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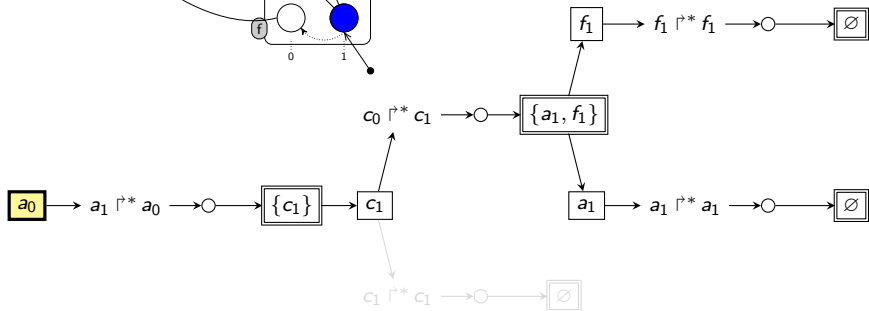
$$\{c_0, f_1\} \rightarrow a_0 \rhd a_1$$

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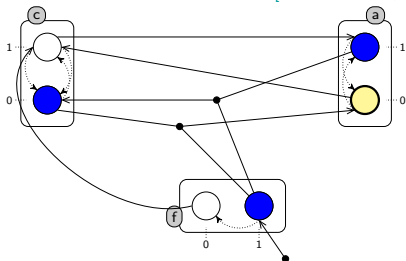
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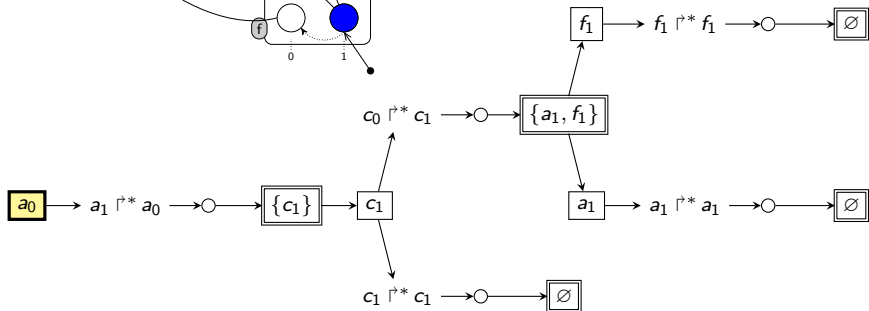
$$\{a_1, f_1\} \rightarrow c_0 \dot{r}^* c_1 \quad :: \quad \{c_1\} \rightarrow a_1 \dot{r}^* a_0$$

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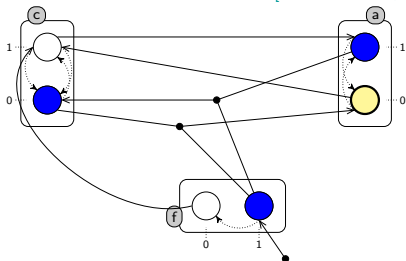
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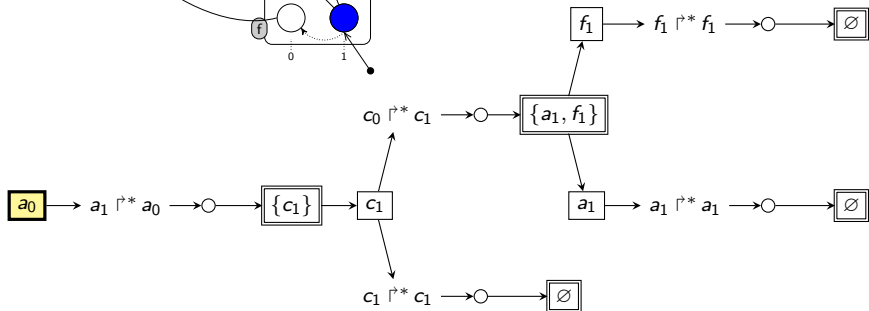
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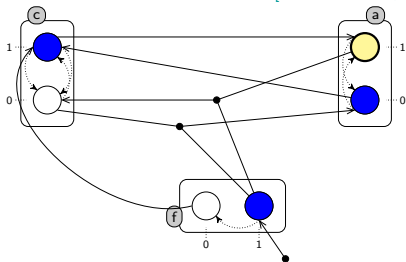
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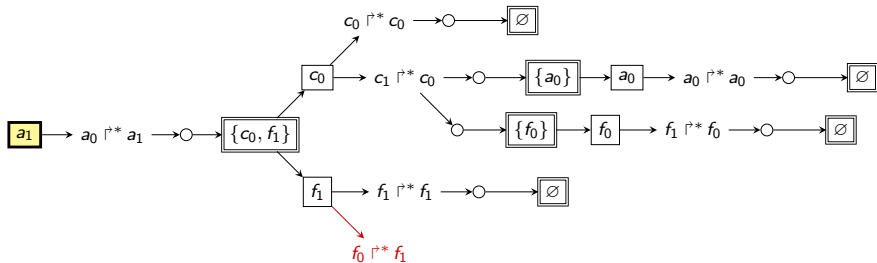
$$\{a_1, f_1\} \rightarrow c_0 \uparrow^* c_1 \quad :: \quad \{c_1\} \rightarrow a_1 \uparrow^* a_0$$

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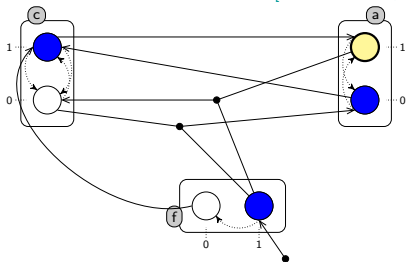
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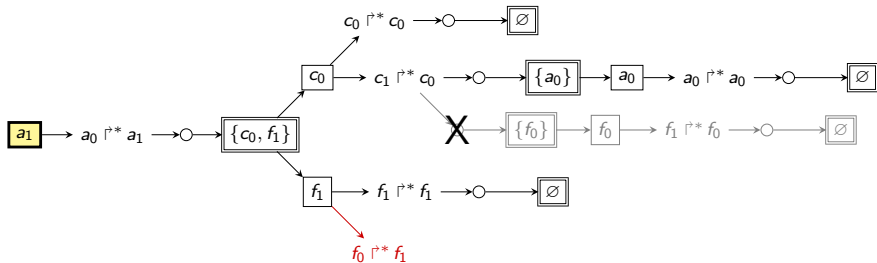
$$\{a_0\} \rightarrow c_1 \uparrow^* c_0 \quad :: \quad \{c_0, f_1\} \rightarrow a_0 \uparrow^* a_1$$

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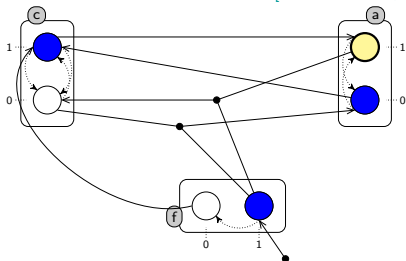
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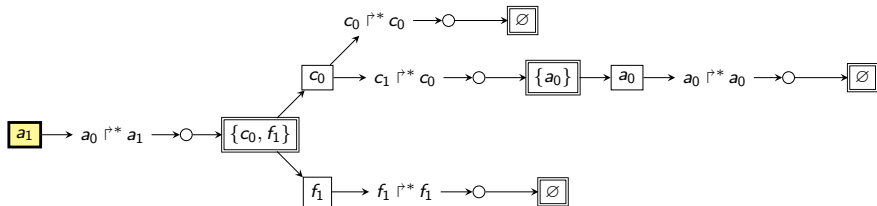
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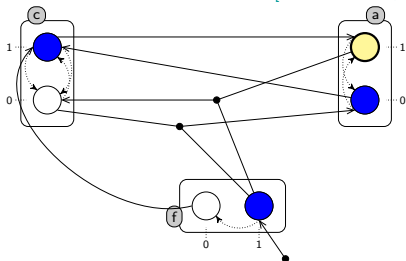
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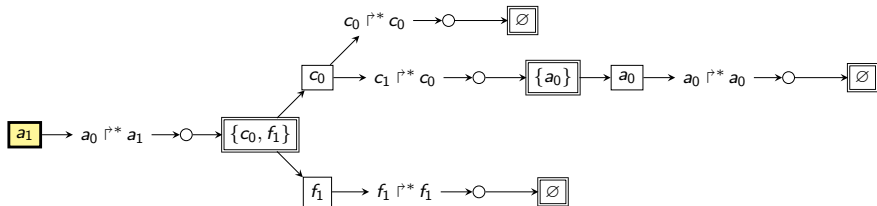
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Implementation of the Abstract Interpretation

Complexity:

- Computation of the local causality graph:
 - Polynomial in the number of automata
 - Exponential in the number of local states of each automata (usually very low, max. 4)
- Analysis of the graph (sufficient condition):
 - Polynomial in the size of the abstract graph
- Enumeration of the subsets of solutions (if needed):
 - Exponential in the size of the abstract graph

→ Very efficient on biological networks: **many components with few local states**

Model	Automata	Actions	States	libddd ¹	GINsim ²	PINT ³
egfr20	35	670	2 ⁶⁴		<1s	0.02s
tcrsig40	54	301	2 ⁷³		∞	0.02s
tcrsig94	133	1124	2 ¹⁹⁴	[>1min - ∞]		0.03s
egfr104	193	2356	2 ³²⁰	[>1min - ∞]		0.16s

¹ LIP6/Move [Couvreur *et al.*, *Lecture Notes in Computer Science*, 2002]

² TAGC/IGC [Chaouiya, Naldi, Thieffry, *Methods in Molecular Biology*, 2012]

³ Loïc Paulevé [<http://loicpauleve.name/pint/>]

egfr20 : Epithelial Growth Factor Receptor (20 components) [Sahin *et al.*, 2009]

egfr104 : Epithelial Growth Factor Receptor (104 components) [Samaga *et al.*, 2009]

tcrsig40 : T-Cell Receptor (40 components) [Klamt *et al.*, 2006]

tcrsig94 : T-Cell Receptor (94 components) [Saez-Rodriguez *et al.*, 2007]

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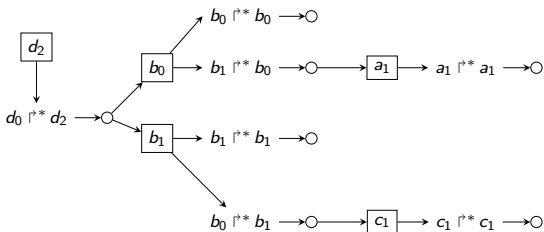
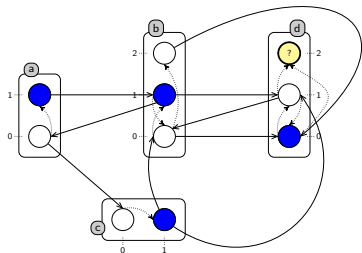
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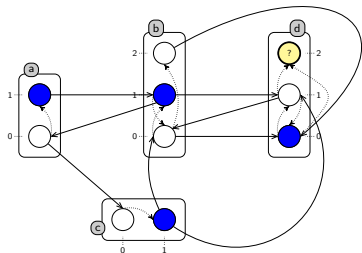
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Under-approximation



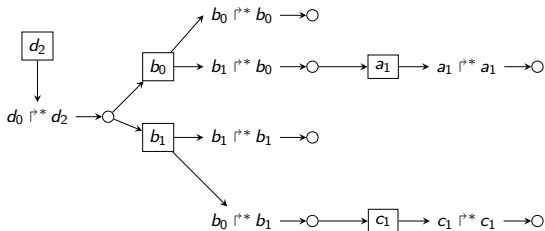
d_2	Required process
$d_0 \overset{r^*}{\dashv} d_2$	Objective
\circ	Solution to an objective

Under-approximation



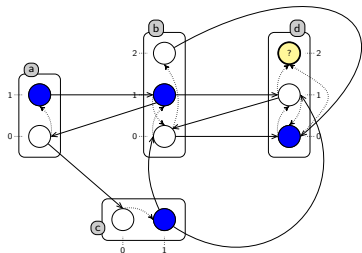
Sufficient condition:

- no cycle
- each objective has a solution



d_2	Required process
$d_0 \text{ r}^* d_2$	Objective
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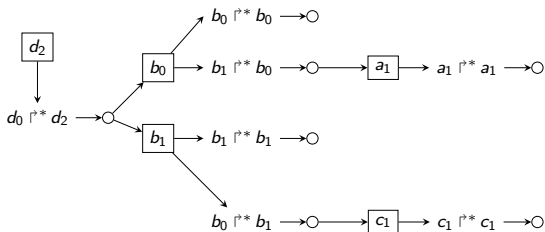
Under-approximation



Sufficient condition:

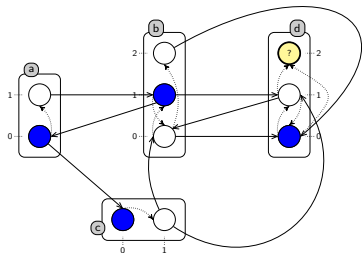
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P is true $\Rightarrow R$ is true



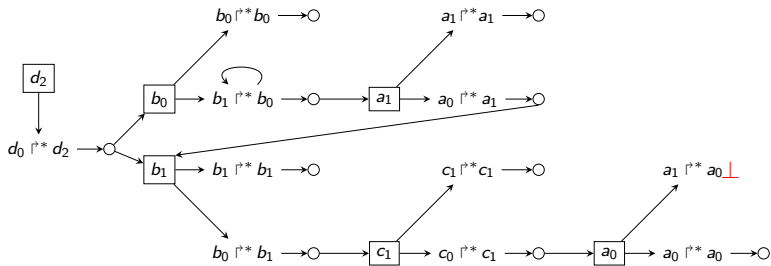
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\circ	Solution to an objective

Under-approximation

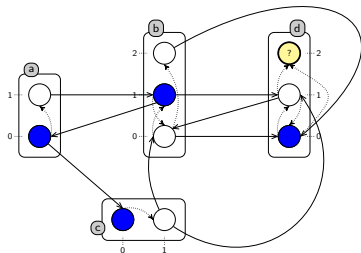


Sufficient condition:

- no cycle
- each objective has a solution



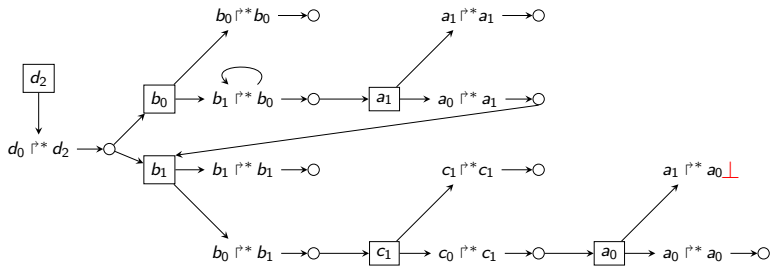
Under-approximation



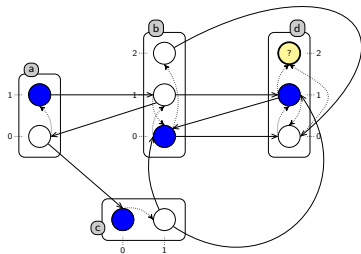
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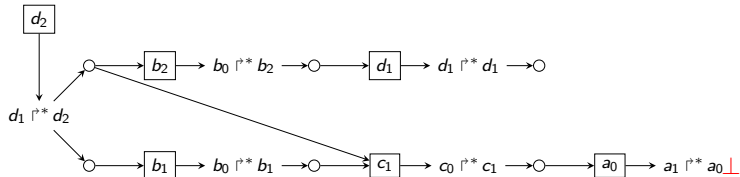
P is false \Rightarrow Inconclusive



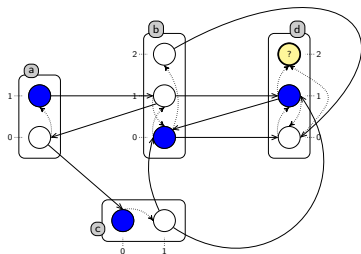
Over-approximation



Necessary condition:



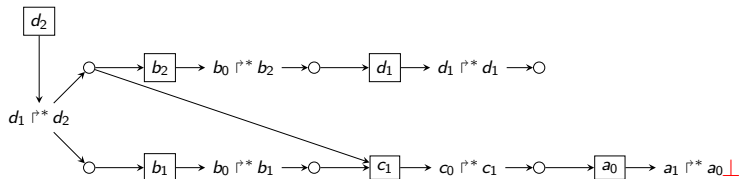
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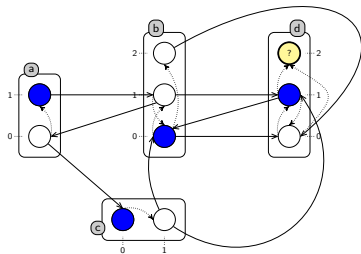
Necessary condition:

There exists a traversal with no cycle

- objective \rightarrow follow **one** solution
- solution \rightarrow follow **all** processes
- process \rightarrow follow **all** objectives



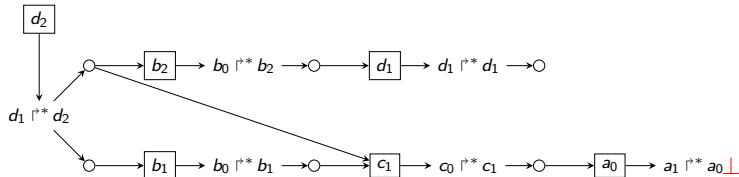
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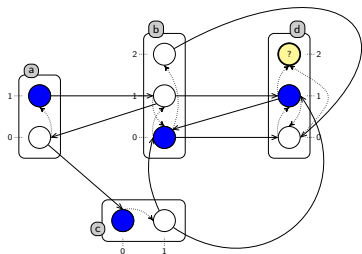


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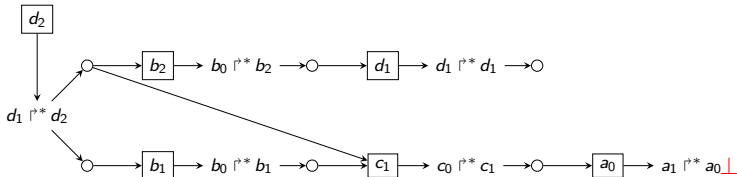
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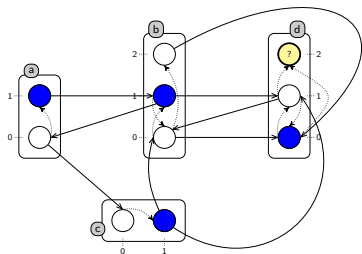
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Q is false ⇒ R is false



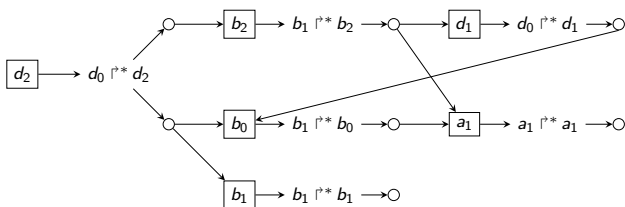


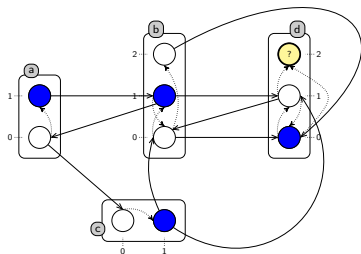
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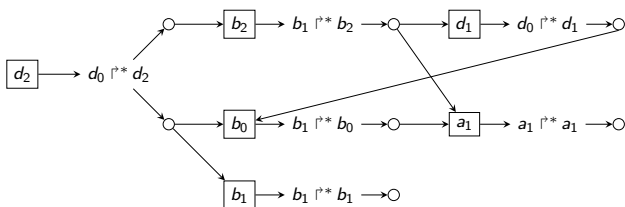
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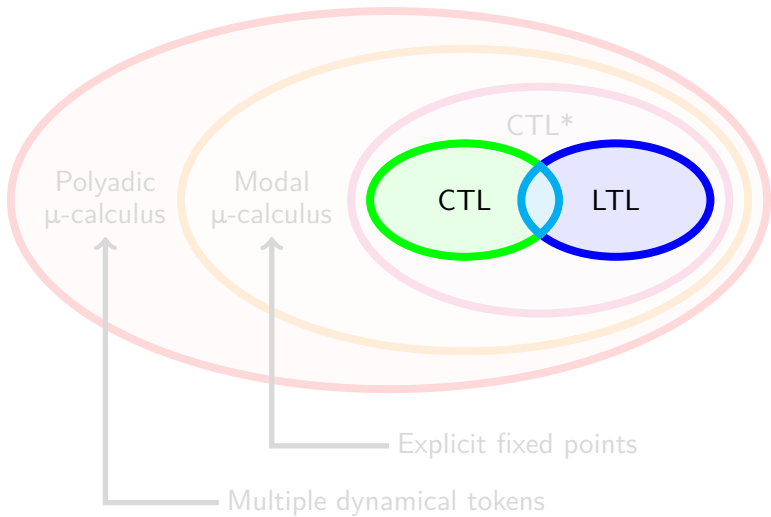
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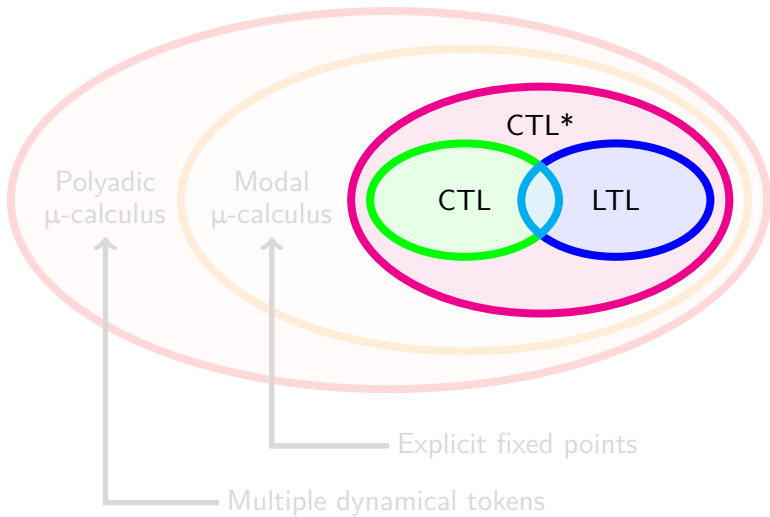
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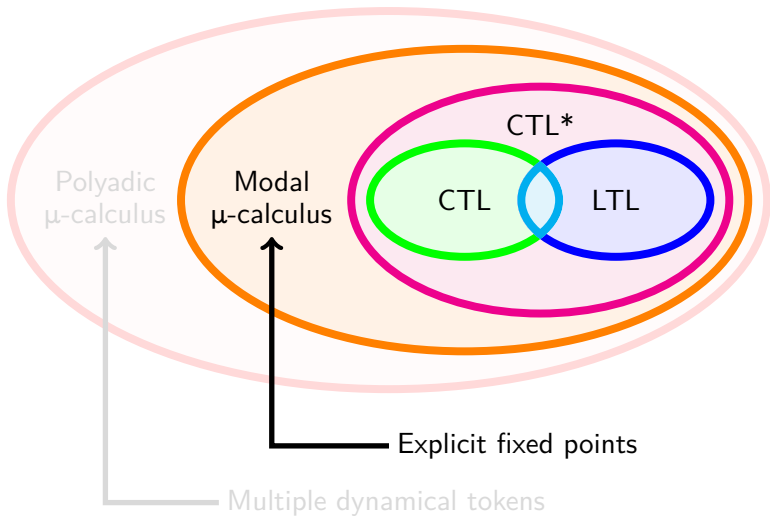
The Polyadic μ -calculus



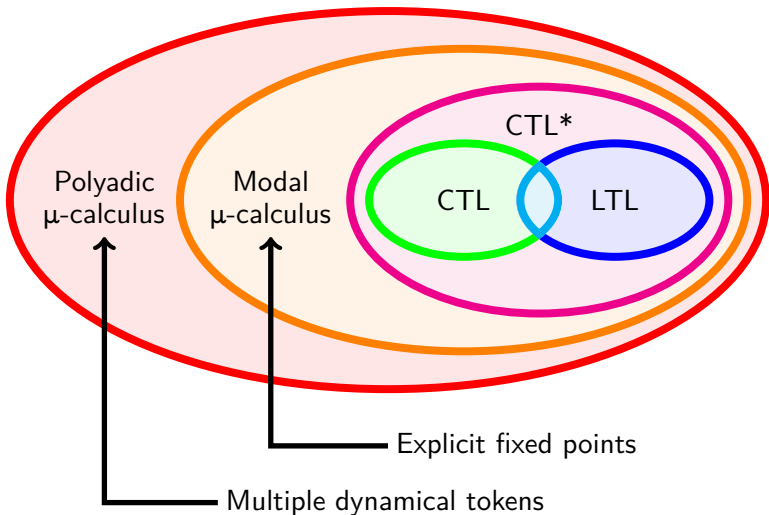
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The Polyadic μ -calculus



Modal and Polyadic μ -calculus

[Andersen, Technical report, 1994]

LTL: Implicit fixed point of the “Until” operator

$p \ U \ q \equiv$ “Either q , or p and the next state also verifies $p \ U \ q$ ”

(Modal) μ -calculus makes such fixed points explicit

$\varphi = p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \diamond\varphi \mid \square\varphi \mid \mu X.\varphi \mid \nu X.\varphi \mid X$

- Basic property: p (“ p is verified in this node”)
- Modal operators: \square (“for all successors”), \diamond (“there exists a successor”)
- Fixed points: μ (least fixed point), ν (greatest fixed point)

Polyadic (modal) μ -calculus allows to manipulate several tokens in parallel

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- $i = j$ (“make tokens i and j point to the same node”)
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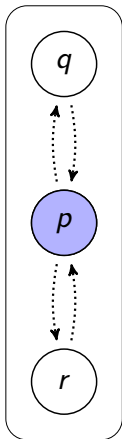
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Examples with Modal μ -calculus

No tokens: only one evolution is studied

Atomic property (p, q, r)

$$\llbracket p \rrbracket = \{p\}$$

$$\llbracket q \vee r \rrbracket = \{q; r\}$$

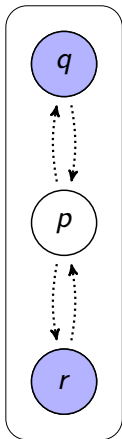
Possible future (“may”)

$$\llbracket \diamond q \rrbracket = \{p\}$$

Necessary future (“must”)

$$\llbracket \square q \rrbracket = \emptyset$$

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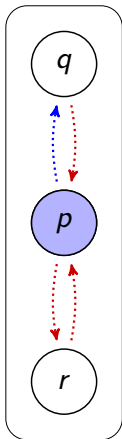
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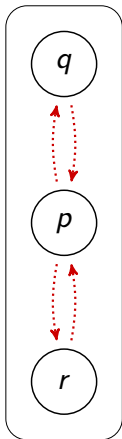
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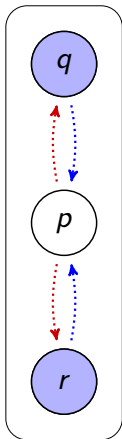
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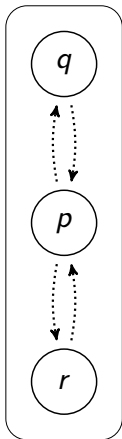
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Examples with Polyadic μ -calculus**Atomic property** (p, q, r)

$$\llbracket p_1 \wedge r_2 \rrbracket = \{(p, r)\}$$

$$\llbracket p_1 \rrbracket = \{(p, p); (p, q); (p, r)\}$$

Token affectation $(i \leftarrow j)$

$$\llbracket \{2 \leftarrow 1\} p_1 \wedge p_2 \rrbracket = \{(p, p); (p, q); (p, r)\}$$

Token comparison $(i = j)$

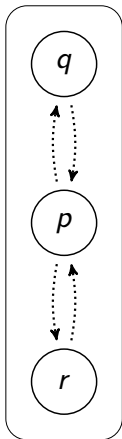
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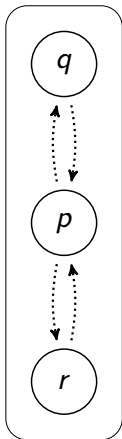
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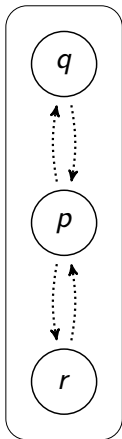
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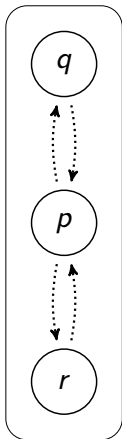
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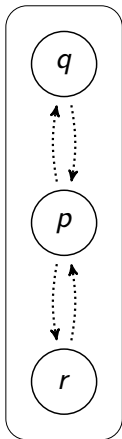
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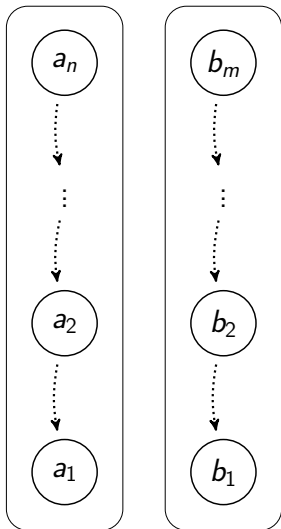
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Examples with Polyadic μ -calculus**Least fixed point (μ)**

$$\phi = \mu X. (\Box_1 \perp \wedge \Box_2 \perp) \vee \Diamond_1 \Diamond_2 X$$

Iterations:

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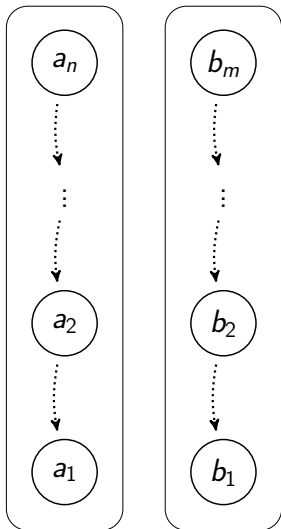
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$$\vdots$$

Generalization:

$$\llbracket \phi \rrbracket = \{(a_i, b_i) \mid i \in [1; \min(m, n)]\}$$

Idea: use one (or n) token per automata

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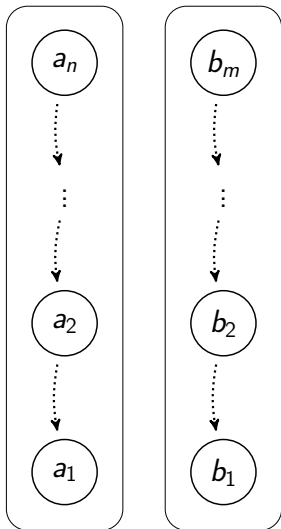
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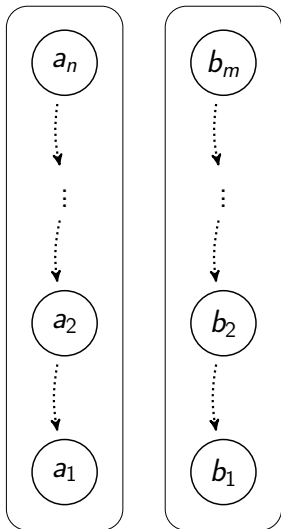
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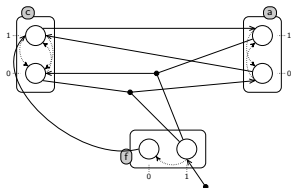
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Applications of the Polyadic μ -calculus

Objective: Unify formulas for many dynamical problems

Not always possible with classical temporal logics (LTL, CTL, CTL*):

1) From the initial state $(a, b, z) = (0, 0, 0)$, is it possible to reach $z = 2$?

$$(a = 0 \wedge b = 0 \wedge z = 0) \Rightarrow \text{EF}(z = 2)$$

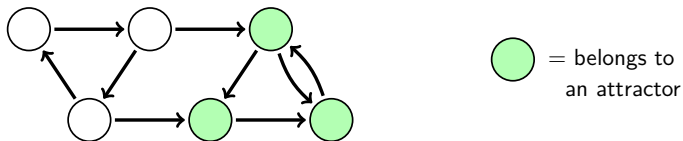
2) Does $(0, 0, 0)$ belong to an attractor?

$$(a = 0 \wedge b = 0 \wedge z = 0) \Rightarrow \text{N}\perp \vee \text{AG}(\text{EF}(a = 0 \wedge b = 0 \wedge z = 0))$$

3) What is the set of attractors of the model?

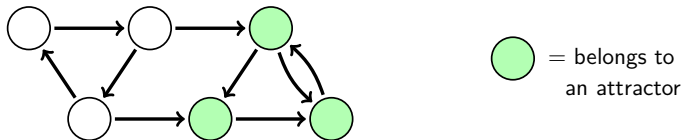
??? — Requires a quantification on the set of all states

Idea: Use polyadic μ -calculus with one token per automata

Search for Attractors with Polyadic μ -calculus

$$\varphi_{\text{att}} = \{y \leftarrow x\} \nu W. \underbrace{(\mu Z. (x = y) \vee (\diamond_x Z))}_{\varphi_{\text{reach}}} \wedge (\underbrace{\square_x W}_{\varphi_{\text{explore}}})$$

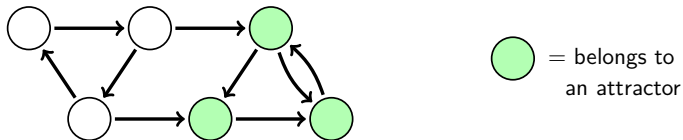
- $\llbracket \varphi_{\text{reach}} \rrbracket = \{(s; t) \mid s \rightarrow^* t\}$
 $\varphi_{\text{reach}} \equiv$ "There exists a path from x to y "
- $\llbracket \varphi_{\text{explore}} \rrbracket = \{(s; t) \mid \forall s', s \rightarrow^* s' \Rightarrow s' \rightarrow^* t\}$
 $\varphi_{\text{explore}} \equiv$ "All successors of x can reach y "
- $\llbracket \varphi_{\text{att}} \rrbracket = \{(s; s) \mid \forall s', s \rightarrow^* s' \Rightarrow s' \rightarrow^* s\}$
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Search for Attractors with Polyadic μ -calculus

$$\varphi_{\text{att}} = \{y \leftarrow x\} \nu W. \underbrace{(\mu Z. (x = y) \vee (\diamond_x Z))}_{\varphi_{\text{reach}}} \wedge (\square_x W)$$

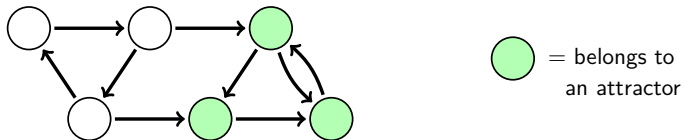
$\underbrace{\hspace{15em}}_{\varphi_{\text{explore}}}$

- $\llbracket \varphi_{\text{reach}} \rrbracket = \{(s; t) \mid s \rightarrow^* t\}$
 $\varphi_{\text{reach}} \equiv$ "There exists a path from x to y "
- $\llbracket \varphi_{\text{explore}} \rrbracket = \{(s; t) \mid \forall s', s \rightarrow^* s' \Rightarrow s' \rightarrow^* t\}$
 $\varphi_{\text{explore}} \equiv$ "All successors of x can reach y "
- $\llbracket \varphi_{\text{att}} \rrbracket = \{(s; s) \mid \forall s', s \rightarrow^* s' \Rightarrow s' \rightarrow^* s\}$
 $\varphi_{\text{att}} \equiv$ " x belongs to an attractor"

Search for Attractors with Polyadic μ -calculus

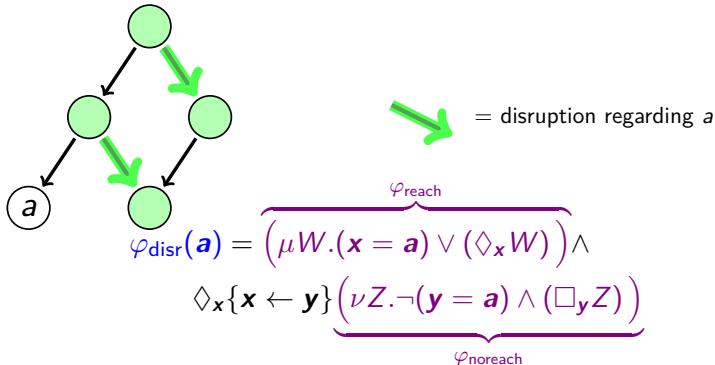
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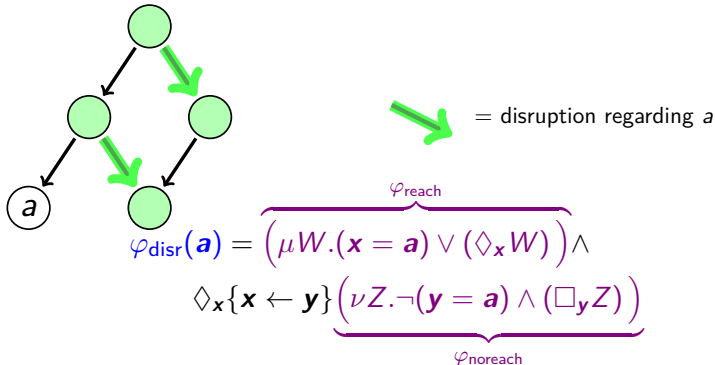
Search for Attractors with Polyadic μ -calculus

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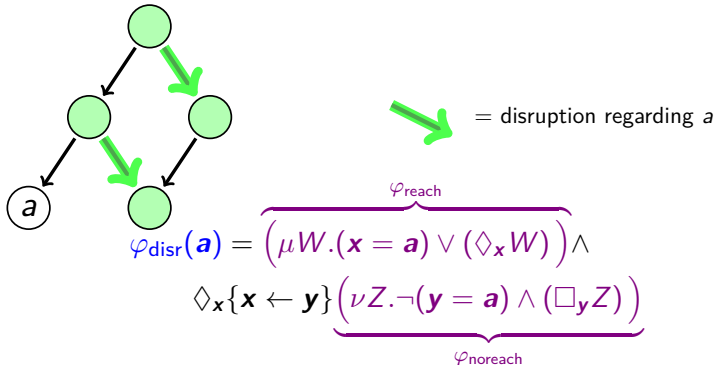
Search for Disruptions with Polyadic μ -calculus

- $\llbracket \varphi_{\text{reach}} \rrbracket = \{(s; t) \mid s \rightarrow^* a\}$
 $\varphi_{\text{reach}} \equiv$ "There exists a path from x to a "
- $\llbracket \varphi_{\text{noreach}} \rrbracket = \{(s; t) \mid \neg(t \rightarrow^* a)\}$
 $\varphi_{\text{noreach}} \equiv$ "There exists no path from y to a "
- $\llbracket \varphi_{\text{disr}} \rrbracket = \{(s; t) \mid s \rightarrow t \wedge s \rightarrow^* a \wedge \neg(t \rightarrow^* a)\}$
 $\varphi_{\text{disr}} \equiv$ "There is a disruption between x and y "

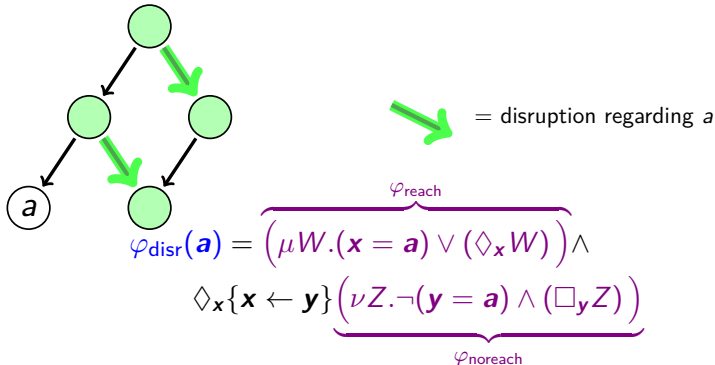
Search for Disruptions with Polyadic μ -calculus

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Search for Disruptions with Polyadic μ -calculus



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Search for Disruptions with Polyadic μ -calculus

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 $\varphi_{\text{disr}} \equiv$ “There is a disruption between x and y ”

Bisimulation with Polyadic μ -calculus

Generic **bisimulation** between two models:

$$\varphi_{\text{bisim}} = \nu X. \left(\bigwedge_{p \in P} p_1 \Leftrightarrow p_2 \right) \wedge (\Box_1 \Diamond_2 X \wedge \Box_2 \Diamond_1 X)$$

Bisimulation only on two sets of **observable components** O and O' :

$$\varphi_{\text{bisim-obs}} = \nu X. \left(\bigwedge_{p \in P} \bigwedge_{(i,j) \in C} p_i \Leftrightarrow p_j \right) \wedge (\Box_O^* \Box_{O'} \Diamond_{O'}^* \Diamond_O X)$$

where:

$$\Box_S \Psi = \bigwedge_{i \in S} \Box_i \Psi$$

$$\Diamond_S \Psi = \bigvee_{i \in S} \Diamond_i \Psi$$

$$\Box_S^* \Psi = \nu Y. \Psi \wedge \Box_S Y$$

$$\Diamond_S^* \Psi = \mu Y. \Psi \vee \Diamond_S Y$$

Conclusion on Polyadic μ -calculus

Properties expressed so far:

- Enumeration of attractors
- Enumeration of disruptions
- Bisimulation between two models (regarding a set of observables)
- Highlighting Zeno behaviors

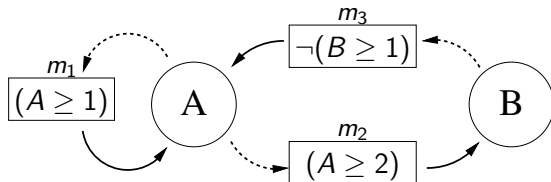
Aim: Unification of properties without quantifiers

Complexity: Exponential (equivalent to building the state graph)

Outlooks:

- New formulas
- Implementation
- Generate μ -calculus formulas? (More readable interface)

Hybrid Thomas Modeling

[Cornillon *et al.*, *Modelling Complex Biological Systems in the Context of Genomics*, 2016]**lacI repressor regulation of the lactose operon in E. Coli**

A = NRI protein + glnG gene + glnA promoter

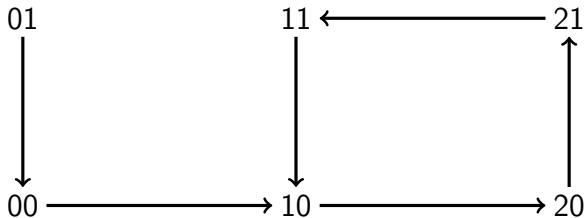
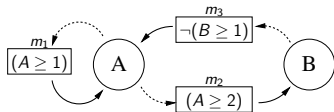
B = lacI gene repressor + glnK promoter

m_1 = glnA promoter is regulated by phosphorylated NRI

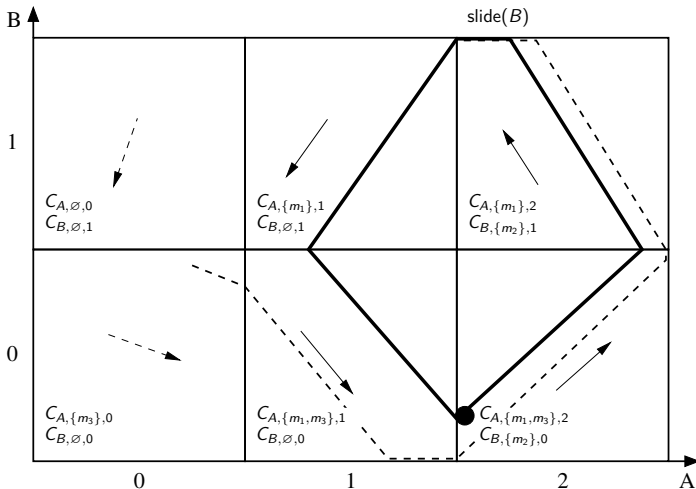
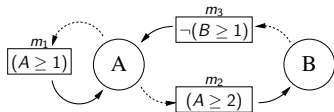
m_2 = glnA promoter is also regulated by lacI

m_3 = lacI gene repressor is regulated by NRIp

Hybrid Thomas Modeling

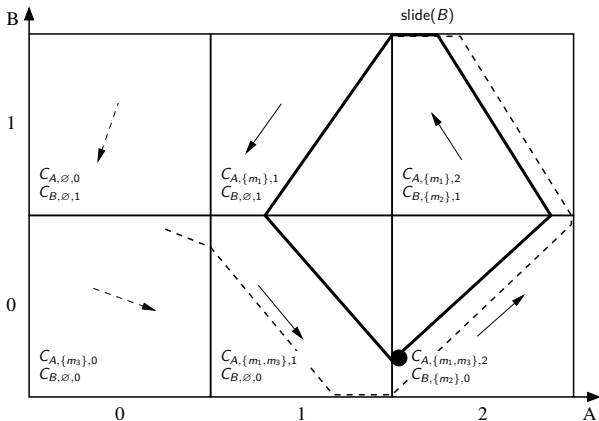


Hybrid Thomas Modeling



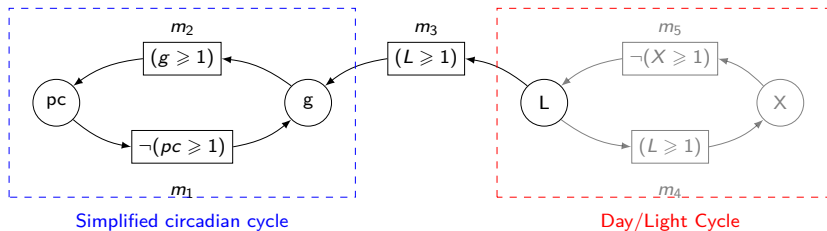
Hybrid Hoare Logic to Infer Parameters

$$\left\{ \begin{array}{l} D_4 \\ H_4 \end{array} \right\} \left(\begin{array}{c} T_4 \\ \top \\ B_+ \end{array} \right); \left(\begin{array}{c} T_3 \\ \text{slide}^+(B) \\ A_- \end{array} \right); \left(\begin{array}{c} T_2 \\ \top \\ B_- \end{array} \right); \left(\begin{array}{c} T_1 \\ \top \\ A_+ \end{array} \right) \left\{ \begin{array}{l} D_0 \equiv (\eta_A = 2 \wedge \eta_B = 0) \\ H_0 \equiv \top \end{array} \right\}$$



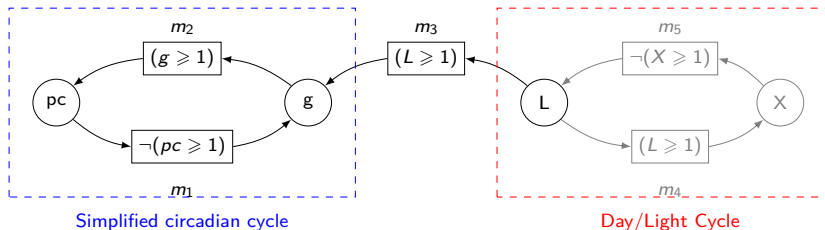
$$\begin{aligned}
H_F \equiv & \left(\neg(C_{B,\emptyset,0} > 0) \vee \neg(1 > \pi_B^{0'} - C_{B,\emptyset,0} \cdot T_1) \right) \\
& \wedge (C_{A,\{m_1,m_3\},1} > 0) \wedge (\pi_A^{1'} = 1 - C_{A,\{m_1,m_3\},1} \cdot T_1) \\
& \wedge \left(\neg(C_{A,\{m_1\},1} > 0) \vee \neg(1 > \pi_A^{1'} - C_{A,\{m_1\},1} \cdot T_2) \right) \\
& \wedge \left((C_{A,\emptyset,0} > 0) \vee \neg(C_{A,\{m_1\},1} < 0) \vee \neg(1 < \pi_A^{1'} - C_{A,\{m_1\},1} \cdot T_2) \right) \\
& \wedge (C_{B,\emptyset,1} < 0) \wedge (1 = 0 - C_{B,\emptyset,1} \cdot T_2) \\
& \wedge \left(\neg(C_{B,\{m_2\},1} < 0) \vee \neg(0 < 1 - C_{B,\{m_2\},1} \cdot T_3) \right) \\
& \wedge (C_{A,\{m_1\},2} < 0 \wedge (\pi_A^{3'} = 0 - C_{A,\{m_1\},2} \cdot T_3)) \\
& \wedge \left(\neg(C_{B,\{m_2\},1} > 0) \vee (0 > 1 - C_{B,\{m_2\},1} \cdot T_3) \right) \\
& \wedge \left(\neg(C_{A,\{m_1,m_3\},2} < 0) \vee \neg(0 < \pi_A^{3'} - C_{A,\{m_1,m_3\},2} \cdot T_4) \right) \\
& \wedge (C_{B,\{m_2\},0} > 0) \wedge (\pi_B^{0'} = 1 - C_{B,\{m_2\},0} \cdot T_4) .
\end{aligned}$$

A Simplified Circadian Cycle Model



$$\begin{aligned}
& (((((((((\pi_g^{0'} = 0.12) \wedge ((\pi_{pc}^{0'} = 0.12) \wedge (\pi_L^{0'} = 0))) \wedge (((\pi_L^1 = 1) \wedge ((C_L, \{m5\}, 0 > 0) \wedge (\pi_L^1 = \\
& (\pi_L^1 - (C_L, \{m5\}, 0 \times 6.6)))))) \wedge (((\neg((C_g, \emptyset, 0 > 0) \wedge (\pi_g^{1'} > (\pi_g^1 - (C_g, \emptyset, 0 \times 6.6)))) \wedge (\neg((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{1'} < \\
& (\pi_{pc}^1 - (C_{pc}, \emptyset, 1 \times 6.6)))) \wedge (\neg((C_X, \emptyset, 0 > 0) \wedge (\pi_X^{1'} > (\pi_X^1 - (C_X, \emptyset, 0 \times 6.6)))))) \wedge (((\pi_L^1 = (1 - \pi_L^{0'})) \wedge ((\pi_g^1 = \pi_g^{0'})) \wedge \\
& ((\pi_{pc}^1 = \pi_{pc}^{0'}) \wedge (\pi_X^1 = \pi_X^{0'})))))) \wedge (((\pi_X^2 = 0) \wedge ((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{2'} = (\pi_X^2 - (C_X, \emptyset, 1 \times 0.6)))))) \wedge (((\neg((C_g, \emptyset, 0 > \\
& 0) \wedge (\pi_g^{2'} > (\pi_g^2 - (C_g, \emptyset, 0 \times 0.6)))) \wedge (\neg((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{2'} < (\pi_{pc}^2 - (C_{pc}, \emptyset, 1 \times 0.6)))) \wedge (\neg((C_L, \emptyset, 0 > \\
& 0) \wedge (\pi_L^{2'} > (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))))) \wedge (((\pi_L^2 = 0) \wedge ((C_L, \emptyset, 0 < 0) \Rightarrow (\pi_L^{2'} < (\pi_L^2 - (C_L, \emptyset, 0 \times 0.6)))) \wedge ((\pi_X^2 = \\
& (1 - \pi_X^{1'})) \wedge ((\pi_g^2 = \pi_g^{1'}) \wedge ((\pi_{pc}^2 = \pi_{pc}^{1'}) \wedge (\pi_L^2 = \pi_L^{1'})))))) \wedge (((\pi_g^3 = 0) \wedge ((C_g, \emptyset, 1 < 0) \wedge (\pi_g^{3'} = \\
& (\pi_g^3 - (C_g, \emptyset, 1 \times 5.4)))) \wedge (\neg((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{3'} < (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge (\neg((C_L, \emptyset, 0 > 0) \wedge (\pi_L^{3'} > \\
& (\pi_L^3 - (C_L, \emptyset, 0 \times 5.4)))) \wedge (\neg((C_X, \emptyset, 1 < 0) \wedge (\pi_X^{3'} < (\pi_X^3 - (C_X, \emptyset, 1 \times 5.4)))))) \wedge (((\pi_{pc}^3 = 1) \wedge ((C_{pc}, \{m2\}, 1 > \\
& 0) \Rightarrow (\pi_{pc}^{3'} > (\pi_{pc}^3 - (C_{pc}, \{m2\}, 1 \times 5.4)))) \wedge ((\pi_g^3 = (1 - \pi_g^{2'})) \wedge ((\pi_{pc}^3 = \pi_{pc}^{2'}) \wedge ((\pi_L^3 = \pi_L^{2'}) \wedge (\pi_X^3 = \\
& \pi_X^{2'})))))) \wedge (((\pi_L^4 = 0) \wedge ((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{4'} = (\pi_L^4 - (C_L, \emptyset, 1 \times 0.47)))) \wedge (\neg((C_g, \{m3\}, 1 < 0) \wedge (\pi_g^{4'} < \\
& (\pi_g^4 - (C_g, \{m3\}, 1 \times 0.47)))) \wedge (\neg((C_{pc}, \{m2\}, 1 < 0) \wedge (\pi_{pc}^{4'} < (\pi_{pc}^4 - (C_{pc}, \{m2\}, 1 \times 0.47)))) \wedge (\neg((C_X, \{m4\}, 1 < \\
& 0) \wedge (\pi_X^{4'} < (\pi_X^4 - (C_X, \{m4\}, 1 \times 0.47)))))) \wedge ((\pi_L^4 = (1 - \pi_L^{3'})) \wedge ((\pi_g^4 = \pi_g^{3'}) \wedge ((\pi_{pc}^4 = \pi_{pc}^{3'}) \wedge (\pi_X^4 = \\
& \pi_X^{3'})))))) \wedge (((\pi_{pc}^5 = 1) \wedge ((C_{pc}, \{m2\}, 0 > 0) \wedge (\pi_{pc}^{5'} = (\pi_{pc}^5 - (C_{pc}, \{m2\}, 0 \times 5.53)))) \wedge (\neg((C_g, \{m1, m3\}, 1 < \\
& 0) \wedge (\pi_g^{5'} < (\pi_g^5 - (C_g, \{m1, m3\}, 1 \times 5.53)))) \wedge (\neg((C_L, \emptyset, 1 < 0) \wedge (\pi_L^{5'} < (\pi_L^5 - (C_L, \emptyset, 1 \times 5.53)))) \wedge (\neg((C_X, \{m4\}, 1 < \\
& 0) \wedge (\pi_X^{5'} < (\pi_X^5 - (C_X, \{m4\}, 1 \times 5.53)))))) \wedge (((\pi_g^5 = 1) \wedge ((C_g, \{m1, m3\}, 1 > 0) \Rightarrow (\pi_g^{5'} > \\
& (\pi_g^5 - (C_g, \{m1, m3\}, 1 \times 5.53)))) \wedge ((\pi_{pc}^5 = (1 - \pi_{pc}^{4'})) \wedge ((\pi_g^5 = \pi_g^{4'}) \wedge ((\pi_L^5 = \pi_L^{4'}) \wedge (\pi_X^5 = \pi_X^{4'})))))) \wedge (((\pi_X^6 = \\
& 1) \wedge ((C_X, \{m4\}, 0 > 0) \wedge (\pi_X^{6'} = (\pi_X^6 - (C_X, \{m4\}, 0 \times 0.6)))) \wedge (\neg((C_g, \{m1, m3\}, 1 < 0) \wedge (\pi_g^{6'} < \\
& (\pi_g^6 - (C_g, \{m1, m3\}, 1 \times 0.6)))) \wedge (\neg((C_{pc}, \{m2\}, 0 > 0) \wedge (\pi_{pc}^{6'} > (\pi_{pc}^6 - (C_{pc}, \{m2\}, 0 \times 0.6)))) \wedge (\neg((C_L, \{m5\}, 1 < \\
& 0) \wedge (\pi_L^{6'} < (\pi_L^6 - (C_L, \{m5\}, 1 \times 0.6)))))) \wedge ((\pi_X^6 = (1 - \pi_X^{5'})) \wedge ((\pi_g^6 = \pi_g^{5'}) \wedge ((\pi_{pc}^6 = \pi_{pc}^{5'}) \wedge (\pi_L^6 = \\
& \pi_L^{5'})))))) \wedge (((\pi_g^7 = 1) \wedge ((C_g, \{m1, m3\}, 0 > 0) \wedge (\pi_g^{7'} = (\pi_g^7 - (C_g, \{m1, m3\}, 0 \times 4.5)))) \wedge (\neg((C_{pc}, \emptyset, 0 > \\
& 0) \wedge (\pi_{pc}^{7'} > (\pi_{pc}^7 - (C_{pc}, \emptyset, 0 \times 4.5)))) \wedge (\neg((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{7'} < (\pi_L^7 - (C_L, \{m5\}, 1 \times 4.5)))) \wedge (\neg((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{7'} > (\pi_X^7 - (C_X, \{m4\}, 0 \times 4.5)))))) \wedge ((\pi_g^7 = (1 - \pi_g^{6'})) \wedge ((\pi_{pc}^7 = \pi_{pc}^{6'}) \wedge ((\pi_L^7 = \pi_L^{6'}) \wedge (\pi_X^7 = \\
& \pi_X^{6'})))))) \wedge (((\pi_{pc}^8 = 0) \wedge ((C_{pc}, \emptyset, 1 < 0) \wedge (\pi_{pc}^{8'} = (\pi_{pc}^8 - (C_{pc}, \emptyset, 1 \times 0.9)))) \wedge (\neg((C_g, \{m3\}, 0 > 0) \wedge (\pi_g^{8'} > \\
& (\pi_g^8 - (C_g, \{m3\}, 0 \times 0.9)))) \wedge (\neg((C_L, \{m5\}, 1 < 0) \wedge (\pi_L^{8'} < (\pi_L^8 - (C_L, \{m5\}, 1 \times 0.9)))) \wedge (\neg((C_X, \{m4\}, 0 > \\
& 0) \wedge (\pi_X^{8'} > (\pi_X^8 - (C_X, \{m4\}, 0 \times 0.9)))))) \wedge ((\pi_{pc}^8 = (1 - \pi_{pc}^{7'})) \wedge ((\pi_g^8 = \pi_g^{7'}) \wedge ((\pi_L^8 = \pi_L^{7'}) \wedge (\pi_X^8 = \pi_X^{7'}))))))
\end{aligned}$$

Manually simplified constraints



Célérités sur g et pc

$$\begin{array}{ll}
 C_{g, \emptyset, 0} < 0 & C_{g, \{pc, L\}, 0} > 0 \\
 C_{g, \emptyset, 1} < 0 & 0 < C_{g, \{pc, L\}, 1} < \frac{1}{5.53} \\
 C_{g, \{L\}, 0} < 0 & C_{pc, \emptyset, 0} < 0 \\
 C_{g, \{L\}, 1} < 0 & C_{pc, \emptyset, 1} = -\frac{0.12}{0.9} \\
 C_{g, \{pc\}, 0} > 0 & 0 < C_{pc, \{g\}, 0} < \frac{1}{6.13} \\
 C_{g, \{pc\}, 1} > 0 & 0 < C_{pc, \{g\}, 1} < \frac{1}{5.4}
 \end{array}$$

Célérités sur L et X

$$\begin{array}{ll}
 -\frac{1}{0.6} < C_{L, \emptyset, 0} < 0 & C_{X, \emptyset, 0} < 0 \\
 C_{L, \emptyset, 1} < 0 & -\frac{1}{6} \leq C_{X, \emptyset, 1} < 0 \\
 C_{L, \{X\}, 0} > 0 & 0 < C_{X, \{L\}, 0} < \frac{1}{5.1} \\
 C_{L, \{X\}, 1} > 0 & C_{X, \{L\}, 1} > 0
 \end{array}$$

Results with compatible constraints from another work

